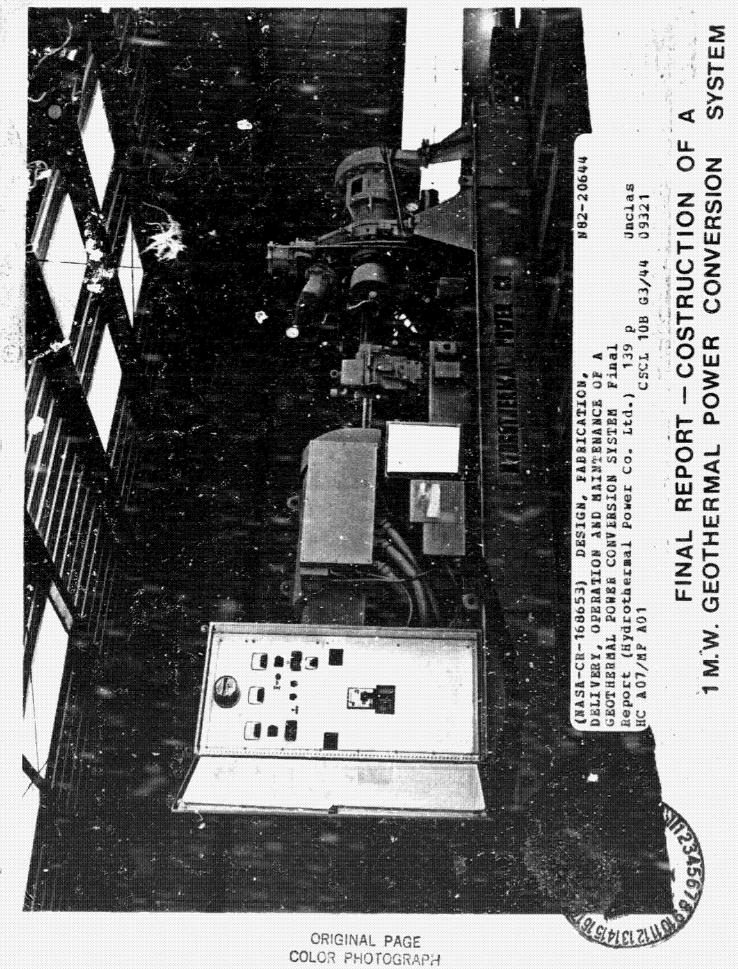
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FINAL REPORT

DESIGN, FABRICATION, DELIVERY, OPERATION AND MAINTENANCE OF A

GEOTHERMAL POWER CONVERSION SYSTEM

THIS WORK WAS PERFORMED FOR THE JET PROPULSION LABORATORY, CALIFORNIA INSTITUTE OF TECHNOLOGY, AND WAS SPONSORED BY THE U.S. DEPARTMENT OF ENERGY THROUGH AN AGREEMENT WITH THE NATIONAL AERONAUTICS AND SPACE ADMINISTRATION.

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TECHNICAL CONTENT STATEMENT

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ABSTRACT

This effort involves the design, fabrication, delivery, operation and maintenance of an HPC 1250 KVA geothermal power conversion system using a helical screw expander as the prime mover. The delivery of the power conversion system was made to the Jet Propulsion Laboratory for evaluation and demonstration with geothermal energy consisting of hot, untreated, corrosive scale-forming brines and/or vapors, including the total flow from geothermal wells of such brines and/or vapors.



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SUMMARY

This effort relates to the design, fabrication, delivery, operation and maintenance of a Hydrothermal Power Co., Ltd. (HPC) 1250 KVA Geothermal Power Conversion System, suitably adapted by HPC for testing and evaluation by the Jet Propulsion Laboratory, California Institute of Technology (JPL).

The system was designed, engineered, and patterned after a 62.5 KVA Power Conversion System previously developed and successfully tested by HPC. The design incorporated Background Patents, Know-how, and Proprietory Rights previously developed and owned by Roger Sprankle and HPC. HPC staff and personnel participated in a preliminary system design review held at JPL covering the 1250 KVA Geothermal Power Conversion System.

The Power Conversion System fabrication included the planning of a fabrication sequence starting with the early issuance of purchase orders for long lead time items and concluding with satisfactory acceptance testing by 77L. The issuance of purchase orders followed competitive bidding. Fabrication included: (1) securing of a Vibration and Torsional Analysis; (2) establishment of a Quality Assurance Program; and (3) the development of a Property Control Procedure, acceptable to the U.S. Government.

To assist in the evaluation process, Calibration and Performance data for both the Speed Reducer and Alternator were obtained.

Copies of the manufacturers' manuals or instructions for each major assembly or sub-assembly were obtained in so far as available.

HPC also provided engineering services to JPI, for the purpose of: (1) planning for support and interface equipment to be provided by JPL to be used in testing and evaluation; (2) the selection of a geothermal test site suitable for performance evaluation; and (3) the development of detailed plans for site preparation and performance evaluation of the Power System.

Following fabrication of the Power System, hydrostatic testing of the process piping and prime mover housing was successfully accomplished at the APC facilities, after which acceptance testing was commenced. During the acceptance testing procedures, four equipment failures were experienced. Acceptance testing was successfully concluded and the System formally delivered on December 4, 1977.

A survey of geothermal well sites was concluded with the selection of well No. 54-3, owned by Phillips Petroleum Co., and located at Roosevelt Hot Springs, near Milford, Utah.

Following on-site inspection of the well and test facilities at Roosevelt Hot Springs, a pre-engineered metal "Butler Building" was ordered, and the Power Conversion System was shipped to Utah. The Power System was then installed and assistance given to the JPL Principal Investigator, Dr. Richard A. McKay, covering details of the testing and evaluation. The operation of the Power System in Utah for the purposes of testing and evaluation by JPL was concluded on November 14, 1979. The Power System and related support and test equipment was shipped to Cerro Pricto, Mexico, on December 1, 1979.

IN RODUCTION

The exploitation of Geothermal Energy is included among the efforts of the U.S. Government to resolve the critical energy needs of its citizens. Geothermal Energy is known to exist in the form of dry-steam which is rare and easily developed. Geothermal Energy exists more abundantly in the form of hot mineralized water wells. Until the development of the Helical Screw Expander, exploitation of hot water resources had been seriously hampered because no suitable prime mover was available for use with the fluids from these wells. It has been necessary to produce a vapor to drive a turbine, either by flashing part of the brine to steam, as is done at Cerro Prieto, Mexico, or by boiling a secondary fluid in a heat exchanger. In the steam flashing process, much energy is lost in the waste hot brine which flows from the steam separators. Although hot mineralized water wells are common, advanced technical development is required to overcome not only the scaling, corrosive, errosive characteristics of the waters, but also the hostile environment in which most of these hot waters are found.

New technology has been developed by Hydrothermal Power Co., Ltd. (HPC) in extensive research resulting in Patents, Know-how, and Proprietory Rights developed in connection with a prototype 62.5 KVA Power System. The prototype HPC Power System utilizes the helical rotory screw expander design as a prime mover driving a conventional 62.5 KVA generator at speeds controlled by a governor. The prototype HPC Power System is portable and

intrinsically self-cleaning in the rotor areas. It is capable of using the liquid-vapor mixture as it comes directly from the well. The prototype unit was successfully tested by operating directly on hot, untreated, corrosive scale forming brines and vapors from wells located at: Cerro Prieto, Mexico (M-7) (M-10); East Mesa, near El Centro, California (62-1); and a geothermal well near Niland, California (Sinclair #4).

The HPC prototype 62.5 KVA power system was the first known power generator to use the total flow of hot untreated brine and vapors directly from a geothermal well. The HPC prototype power system disclosed some interesting and useful technology which HPC believed would assist in the early utilization of energy from geothermal brines. The following observations and conclusions were offered in support of this belief. Paragraphs 2 through 5 of the following were taken from the writings of R. McKay, JPL.

- 1. The helical screw expander is a pure rotary, positive displacement machine. The positive displacement feature allows the machine to operate effectively over a broad range of geothermal conditions. The pure rotary motion allows operation in a much higher speed range than reciprocating machines allow. Thus, helical rotary screw expanders up to the fifty MW size range are readily feasible and are ideally suited to geothermal applications.
- 2. As a geothermal prime mover, the HPC helical screw expander is a total flow machine which can expand directly the vapor that is continuously being produced

from the hot saturated liquid as it decreases in pressure during its passage through the expander. Appendix E for cutaway view of prime mover.) The effect is that of an infinite series of stages of steam flashers, all within the prime mover. Thus, the mass flow of vapor increases continuously as the pressure drops throughout the expansion process and the total fluid is carried all the way to the lowest expansion process approximates an isentropic pressure. The expansion from the saturated liquid line for the total The geothermal fluid flows through an internal flow. nozzle control valve and at high velocity enters the high pressure pockets formed by the meshed rotors, the rotor case bore surfaces, and the case end face. As the rotors turn, the pocket elongates, splits into a V, and moves away from the inlet port. With continued rotation, the V lenghtens, expanding successively as the point of meshing of the scris appears to retreat axially from the expanding fluid. The expanded fluid at low pressure is then discharged into the exhaust port.

3. Conditions for mineral precipitation from saturated brines within the expander occur for several interrelated reasons, including temperature decrease, pressure decrease, solvent removal, turbulence and the presence of nucleation sites. The internal surfaces of the expander serve as mineral deposition sites. Mineral deposition on these surfaces accomplishes several

beneficial results. The thickness of the mineral layer increases until the rotor-to-rotor and rotor-to-case leakage clearances disappear and the mineralized surfaces are continually lapped; steady state is reached. The loss of leakage clearances results in substantia increase in the efficiency of the expander. clearance removal mechanism makes possible the use of less expensive fabrication and machining procedures during manufacture, and also makes the expander selfhealing in the event that scarring of the case or rotors should occur. Moreover, the mineral layer has been demonstrated to provide excellent protection of the case and rotors against corrosion. This protection provides greater flexibility in the selection of relatively low cost materials of construction. Similarly erosion is minimal, either because the scale layer forms a protective coating or because the fluid velocities within the machine are not high, or both.

4. The lapping process associated with the minerals which are deposited on the machine surfaces within the expander is a source of suspended nuclei for additional mineral deposition and crystallization within the expander. In an experimental investigation of mineral deposition carried out in October, 1971, while operating a prior helical screw expander on Well M-10 at Cerro Prietc, HPC staff observed that mineral deposition occured either almost exclusively within the expander or on the seed particle, traveling with the exhaust brine.

After 307 hours of operation, the deposits ranged from 5/32 inc. at the expander exhaust port to 1/64 in. 50 feet downstream. In the absence of the expander, the same well and feedline plugged shut a 12 in. exhaust pipe in approximately 80 hours. This characteristic of mineral precipitation occurring preferentially within the expander, either on the expander surfaces which are self-cleaning, or harmlessly in suspension, is highly beneficial. The tendency to deposit scale downstream appears to be neglible, at least along an isothermal path. This is important, not only for interstaging, but also in waste lines.

5. Essential to high engine efficiency is small leakage past the rotors. This requires small clearances, both rotor-to-rotor and rotor-to-case. The minute clearances brought about by the wet lapping of the mineral deposits in the geothermal expander leads to maximum efficiences in this new unique application.

Three energy conversion concepts -- the Flashed Steam System, the Binary Cycle System, and the Total Flow System -- are present contenders for producing electricity from hot-water geothermal resources. In the Total Flow System, as represented by the HPC Helical Rotary Screw Expander Power System, the hot wellhead product follows an isentropic expansion directly from the wellhead through the prime mover to the exhaust pressure and temperature. The system is thermodynamically the simplest and is theoretically optimum.

The successful operation of the HPC 62.5 KVA prototype system led HPC to the conclusion that the design and construction of a commercial size system was possible. In April of 1973, two engineers from the Jet Propulsion Laboratory toured the geothermal site at Cerro Prieto, Mexico, and observed the 62.5 KVA power plant in operation. They agreed with the conclusions of HPC staff.

A project proposal calling for the construction and evaluation of an HPC designed 1250 KVA Geothermal Power System was prepared by the Jet Propulsion Laboratory in consulation with HPC, and submitted to, and eventually approved by, The National Science Foundation. The project was thereafter preempted by the Energy Research and Development Administration (ERDA) and then by the U.S. Department of Energy, (DOE), Division of Geothermal Energy, present sponsors of the project.

The project plan called for the construction of a modular HPC 1250 KVA Geothermal Pows. System, incorporating the helical rotory screw expanser as the prime mover, to be operated on total flow brine with an evaluation of the power system's mechanical and thermodynamic performance by JPL. An interagency agreement between ERDA and NASA resulted in the authorization of and financing for the project. Dr. Richard A. McKay, proposal author, was assigned to plan, co-ordinate and manage the project as technical manager and principal investigator on behalf of JPL and NASA.

Jet Propulsion Laboratory contracted with HPC for design, fabrication, delivery, operation and maintenance of an HPC 1250 RVA Geothermal Power Conversion System, with testing and evaluation to be carried out by JPL. An impartial mechanical and thermodynamic performance report and evaluation are the responsibility of JPL.

TECHNICAL DISCUSSION

The design and engineering for the 1250 KVA Power Conversion System built during the effort being reported were based upon a prototype 62.5 KVA Power Conversion System previously designed, engineered and constructed by Hydrothermal Power Co., Ltd. (HPC). The design incorporated Background Patents, Know-How and Proprietory Rights previously developed and owned by HPC. Appendix A is a Descriptive Specification of the 1250 KVA Power Conversion System.

The following discussion has been arranged in chronological order for ease of understanding. The time period is from start of plant construction, January 16, 1976, through shipment from the Roosevelt Hot Springs, Utah test site to Cerro Prieto, Mexico, on December 1, 1979.

Immediately following contract execution, various manufacturers were contacted for current quotations covering price and availability for major long-lead time items. Consistent with competitive bidding, "Requests for Quotations," were issued. A copy of the face sheet of the HPC, "Request for Quotation," form is attached as Apendix B.

The planned method of construction of the prime mover housing was changed from casting to fabricating. A meeting at the Cerro Prieto Geothermal Plant was conducted with the CFE Dept. of Geothermal Studies covering their recommended materials of construction. Their recommendations were co-ordinated with material availability from suppliers. Their recommendations also covered materials of construction for the entire plant.

A basic layout of the expander housing was drafted. The layout was detailed into shop drawings soon after rotor details were finalized. Appointments were arranged with shaft seal and bearing manufacturers. Appendix C contains facsimile copies of records of the chemical analysis, "hanical analysis, and non-destructive testing records relative to the rotor forging. Appendix D contains facsimile copies of chemical and mechanical analysis of material used in the prime mover housing. Appendix E shows a cutaway view of the prime mover.

A meeting with a bearing supplier covered the thrust and journal bearings. Their quotation included strain gauges and thermocouples in the thrust bearing pads and thermocouples in the journal bearing babbitt. All main bearings were sized with a unit loading of 150 psi or less. A meeting was held with a shaft seal supplier. Various designs were discussed, including the shaft seal design in the existing HPC 62.5 KVA Power System.

In March, 1976, a meeting was held with JPL personnel covering the electrical interfacing between the power System and Jet Propulsion Laboratory evaluation equipment. All major electrical equipment belonging to the Power System and supplied by HPC was made ready for purchase. Minor details of interfacing were scheduled for accomplishment during assembly. Suggestions concerning the alternator details were made by the JPL technical staff and these details incorporated into the alternator design. Also, the raw data for the vibration and torsional analysis of the main drive train was assembled and made ready for the actual analysis. In addition, the shop layout and supplies were organized and prepared for the delivery of the first raw materials.

In the following three (3) months, details of the prime mover were attended to and prepared for shop drawings. Items covered included the shaft seals, bearings, O-rings, shims and gaskets, bolt size and loading, and the housing fabrication sequence. Items addressed with respect to the entire power plant included the skid pad, protective coatings, minor electrical details, and the governor control response characteristics. Governing of the plant is achieved by controlling the position of a moveable nozzle component which forms part of the high pressure port of the prime mover. The hydraulic coupling between the governor and the control nozzle is identical to the existing 62.5 KVA power plant linkage, except for a second stage hydraulic amplifier to handle the greater work load of the larger control nozzle component.

In order to assure quality and conformity between purchase orders and purchased parts, an approved Quality Control Procedure was adopted. A record has been maintained of all signi cant purchased parts. Appendix F sets forth the established Quality Control Procedure and a copy of the form for records maintained.

While construction of the prime mover housing progressed routinely, attention was also directed to the safety shutdown system and engineering data for the lubrication console.

The basic safety shutdown system consists of a gate valve located in the inlet pipeline to the ome mover. This gate valve is held open by a double acting cylinder which, on loss of electrical signal, will close the value automatically. Various sensing switches throughout the plant control this electrical signal. In addition the governor control nozzle trips to

the closed position on loss of electrical signal due to a fault. The gate valve construction was chosen with the assistance of engineers from Cerro Prieto, Mexico, and contains both design and materials known to be tolerant to corrosive geothermal brines. Apper lix B shows material used for gate valve construction.

The requirements to the lubrication system involve the prime mover, speed reducer, and governor system. The prime mover requirements entail the bearings, seals, timing gears, and the heat transfer through the housing. The speed reducer requirements involve the bearings and gears. The governor system requirements include the governor, hydraulic servo, hydraulic amplifier and double acting cylinder. A small requirement is also necessary for the automatic gate stop valve. After these items were defined, and with their requirements known, the lubrication console was sized accordingly and construction started.

The main drive couplings are of the flexible gear type. The high speed coupling is a spacer type gear coupling with a NEMA standard diametric taper hub on the expander side for ease of removal. Both hubs have puller holes. The low speed coupling is an overload type year coupling. Both of these hubs have puller holes. The puller holes allow the easy removal of the hubs for gear interlange in the speed reducer.

F llowing design completion of the main drive train couplings, a vibration and torsional analysis of the main drive train was performed. Appendix G contains the vibration and torsional analysis.

Concurrently with the plant construction, assistance was given to JPL in a site selection survey for plant evaluation. Various potential sites were visited in August, October, December, and January, 1977. As part of the site selection survey, a tour was made of the Roosevelt Hot Springs area in Utah, being developed by Phillips Petroleum Co. This site was eventually chosen as having the best potential of fulfilling the needs of the evaluation project. Major factors affecting this choice were the availability of effluent disposal, high wellhead flow and enthalpy, potential continuous operation of the well, and well flow stability.

From January through March, 1977, a major effort was extended to the welding, grinding, machining, and fabrication of the prime mover. The housing midsection advanced through numerous steps, including the surfacing of the end faces, finish welding to the exhaust section, and set-up for boring. The inlet port and nozzle area was organized, prepared for shaping, and shaped for acceptance of the control nozzle component. The housing was aligned and pinned and the midsection finish machined. The inlet port flange and foot pads were welded to the housing and the housing was assembled in preparation for hydrostatic testing. minor items were fabricated such as special tools for assembly and disassembly of the prime mover, an alignment fixture to position the prime mover on the skid pad, and hydrostatic test pump equipment.

The hydrostatic testing of the prime mover housing involved two regions, the high pressure region and exhaust region. For hydrostatic testing, the high pressure region was isolated from the exhaust region with a bulkhead fixture. On April 7, the mid and low pressure regions were hydrostatically tested to 450 PSIG, following the <u>ASME Boiler and Pressure Vessel Code</u>. On June 29, the high pressure region was hydrostatically tested to 1080 PSIG, following the <u>ASME Boiler and Pressure Vessel Code</u>. A hydrostatic test was also conducted on all onboard inlet piping prior to installation.

Concurrently with hydrostatic testing, numerous other items were completed. Inspection and acceptance testing was made on the speed reducer. Appendix H contains efficiency and performance curves for the speed reducer. The alternator had been tested and inspected earlier. Appendix I contains efficiency and performance curves relating to the alternator.

The prime mover was assembled for an alignment, clearance check, and pinning of mating parts. Rotor machining and hard-facing were completed and the rotors balanced with bearing, seal, and coupling parts attached. Residual imbalance is shown in Appendix J. Hydraulic plumbing was completed for the shaft seals, governor, bearings, and buffer grease system. Installation of electrical switchgear, wiring, and instrumentation was partially completed with calibration of safety stop sensors.

Subsequent to the hydrostatic testing, the assembled prime mover, speed reducer, and alternator were mounted and aligned on the main skid pad. The alternator was mounted first and bolted directly to the skid pad and aligned with studs to the alternator feet. Next, the speed reducer was mounted to the main

skid. Alignment was effected by using thermoplastic grout, brass shims and alignment studs to the speed reducer feet. Finally, the prime mover was aligned to the speed reducer in the same fashion. With the main drive train mounted and aligned, the drive couplings were installed and attention directed towards the completion of sub-systems in preparation for dynamic plant testing.

Prior to dynamic testing, planning was done by staff from HPC and JPL and a procedure formulated entitled, "System Test and Acceptance Procedure". The procedure followed by both JPL and HPC staff is set forth in Appendix K.

Dynamic plant testing was scheduled for August 13, 1977. The first half of the month involved preparation for this testing. A faulty overspeed switch was replaced, and a design improvement was made to the governor override solenoid valves involving the hydraulic port location on the governor.

For dynamic testing, compressed air was used as the motive fluid to drive the prime mover. The dynamic testing was terminated early, after a spline drive to the governor sheared, and in the process destroyed much of the governor. The problem was later diagnosed as a tight fitting spline, allowing no radial mis-alignment between the governor input drive and female rotor shaft. Arrangements were made with the governor manufacturer for a repaired governor, and the clearances on the spline coupling were increased to allow for radial run-out.

The dynamic tesing was re-scheduled for September 14. Preparation included general check-out, replacement of a hand pump with an electric drive pump, and adjustments to the response time in the governor hydraulic system. The acceptance testing was not completed due to a seal failure on the male rotor high pressure end seal assembly. Subsequent to inspection and consultation with the seal manufacturer it was concluded that the failure was due to an extreme overpressure in the supply oil to the seals and lack of proper relief valves for that pressure. It is believed that the extreme overpressure was caused by normal seal heating and subsequent fluid expansion within the seal assembly. Relief valves were installed on the supply oil lines to each of the seals. In addition, the male rotor high pressure end seal assembly was re-installed with only 4 of its original 7 seals. This reduced frictional heating.

On October 20, the power plant was again operated on air. After approximately forty (40) minutes of operation and acceptance testing, rotor contact was noticed. The test run was terminated and re-scheduled for the following week after the timing gears were re-set. It is believed that a contributing factor to the rotor contact was housing distortion due to the cooling effect of the air as it expanded across the prime mover.

On October 27, the power plant was again operated on air. The plant was operated for approximately 1 hour, 45 minutes, during which most of the acceptance testing procedure was completed. The testing was again terminated by a failure on the male rotor high pressure end seal assembly. Subsequent investigation revealed inadequate clearances between the stationary and rotating part due to thermal growth. Added clearances were machined into the seals and acceptance testing scheduled for December 4, 1977.

On December 4, acceptance testing was successfully completed after approximately four (4) hours of continuous operation and satisfactory completion of all items covered in the "System Test and Acceptance Procedure".

As specified in the contract, construction of the Power Conversion System was scheduled for 15 months at a cost of \$477,791. Actual construction time was 22 months and 19 days at an aproximate cost of \$481,000. The schedule variation is attributed essentially to delays in issuance of initial purchase orders and mechanical problems during acceptance testing.

Following successful delivery of the plant, effort was given to: modifications to the plant needed for operation on Phillips Well 54-3; packaging; and site preparation. The modifications to the plant involved the re-design, ordering and installation of electrical switchgear suitable for the re-injection pumps required for this particular test site. The site preparation involved grading, placement of cross timbers onto which the plant was positioned, and site layout for the location of major items such as the data van, load bank, auxiliary power plant, exhaust holding tanks, shop facilities and living quarters. Appendix L contains a schematic of the Utah test site layout.

Prior to shipment of the Power Conversion system, it became evident to Hydrothermal Power Co. that shop facilities and support at the remote Roosevelt Test Site were unavailable for the project needs. To fill this need, HPC constructed a mobile shop trailer. The shop was well equipped with tools to provide a wide range of services such as welding, cutting, grinding, threading, cleaning,

and painting. In addition, the shop contained a broad selection of fittings such as valves, tubing, gaskets, and packing materials. The shop trailer proved to be a tremendous asset at the test site.

The Power Conversion System was delivered to the test site on February 1, 1978. The balance of the month was expended in off-loading the system, site preparation for and placing of the exhaust holding tanks, and errecting a protective steel building for the power system. Assistance was given in the planning for the inlet and exhaust piping, placement of the test van and other test facilities.

Prior to running the Power System, a procedure for logging and recording various important plant parameters, such oil flows, pressures and temperatures was developed. The recording and logging procedure was planned to compliment the testing data to be recorded by the computer system housed in the JPL Data As a part of the logging and recording procedures, forms Van. were prepared suitable for manual logging and subsequent filing. Appendix M is a copy of the logging form. The initial time period for recording was every one-half hour, but was soon changed to one hour intervals as confidence increased in the process and equip-Items concerning the plant status were also logged in the ment. data van as part of the test data. In addition, periodic recordings were taken of the main drive train vibration level at eight (8) marked locations. A vibration meter was used for this purpose (Sonidet Meter, Cardwell Condenser Corp.). Also spot visual checks were continually made during operation.

The first half of March, 1978, was expended in assisting the Principal Investigator, Dr. Richard McKay, in the completion of the inlet and exhaust piping and data aquisition system. The first run was on March 16. After approximately fifteen (15) minutes running, a governor spline broke. Repairs were made to the governor and the system was again run on March 21. During the balance of the month, the system was run at intervals, being shut down frequently while changes in the inlet piping and inlet piping controls were made under the direction of the Principal Investigator.

Operation and testing at the Utah test site can be broken into two (2) catagories: Power System Operation and Site Process Operation. The Power System involves only the process from the inlet flange to the exhaust flange of the HPC Power System. The Site Process includes everything from the wellhead through the Power System to the disposal well located one and four tenths (1.4) miles from the wellhead.

Initial operation of the Power System involved becoming familiar with the site process and then adjusting the process controls for stable, steady operation; a critical requirement for testing. A significant improvement was made to the site process operation when the wellhead separator level was instrumentated and proper level maintained.

A problem that persisted throughout all the testing involved the inlet piping from the point where the steam and water were mixed to the point where the mixture entered the prime mover. The problem manifested itself in the form of unstable flow and slugging which prevented stable 60 cycle operation, forcing the plant to vary at times ± 2% in frequency. This unstable flow was most noticeable between an inlet quality of 1% and 10% steam. With qualities g eater than 10% steam, the higher flow velocities appeared to assist in mixing. Different diameters of inlet piping were tried with some success, in an attempt to prevent unstable and slugging flow. With zero steam quality or all liquid fee, the plant operation was surprisingly smooth and steady. However, under some conditions, where the inlet control valve was par-' lay open, water hammer would occur in the inlet piping.

Concurrently with the effort to improve the unstable inlet flow, efforts were made to improve the governor system performance. Some success was obtained by cutting throatling notches into the spool for the hydraulic amplifier.

Another problem area during plant operation involved silica scale buildup in the waste disposal pump strainers. Part of the pipeline between the waste holding tanks and the pump inlets took advantage of an existing used pipe, previously installed for other purposes by Phillips Petroleum Co. This pipe length continuously shed scale which clogged the strainer to the pumps along with new scale which was continuously precipitating during plant operation. Much of the used pipe was removed with some improvement to this problem. By alternately switching between the duplex pumps, plant operation was maintained with repetitive strainer cleaning as required.

Another problem of a more serious nature involved the prime mover shaft seals. As testing and plant operation progressed, the

seal leakage rate continued to increase. On April 23, inspection revealed that the male low pressure seal leakage rate was excessive. Subsequent removal revealed a cracial seal sleeve and serious errosion, with silica scale build-up. The seal assembly was replaced. In the hope of preventing another failure air was injected through pre-existing ports to the high pressure end seals. Pre-existing ports were not available to the low pressure end seals and could not be machined into the housing in the time available. Well shut-in was scheduled for June 1, 1978. The decision was made to continue testing with the recognized risk of another seal failure.

On May 3:, 1978, one day before the scheduled termination of the Utah testing, the same shaft seal failed in a catastrophic manner. The seal failure friction welded the seal sleeve to the shaft, ruptured and demolished the seal assembly, bent the shaft, and due to excessive heating, melted the adjacent bearing babbitt.

Repair of the plant began subsequent to the post calibration of the evaluation instrumentation, preservation and storage of process equipment, and well site cleanup. Repair of the power plant was centered around repair and re-designing of the shaft seals and improvement of other plant aspects for better all around performance.

The fundamental design change to the shaft seals involved the addition of a fresh water flow across the seal area exposed to the brine process. This fresh water acts as a shield, or buffer, preventing mineral build-up in the seal assemblies.

To accomodate the new seal design, the safety shutdown system was changed. The change involved the installation of flow switches to each seal flush water line. The change also involved differential pressure switches and gauges installed on the oil/flush water system on each seal assembly. These switches are all wired in series with the existing shaft seal pressure relay. In addition, to handle the additional power requirements of the 24 VDC system; the batteries and battery charger were changed to a larger size.

At the Utah test site, there was no source of fresh water for use across the shaft seals. For the continued Utah testing, the most readily available source of flush water was determined to be steam condensate. The equipment involved is a steam/exhaust brine heat exchanger located in the exhaust holding tanks and then a condensate/air heat exchanger to supply a holding tank with condensate at a temperature < 160°F. The holding tank is used to supply a metering pump which feeds each seal assembly.

experienced an abrupt load loss of more than 500 KW with subsequent overspeed and automatic shutdown. Proper governor design should be responsive enough to allow full load changes without overspeed or underspeed shutdown. A design improvement of the plant involved a custom built hydraulic amplifier and increasing the hydraulic oil supply for quicker governor response and greater work rating.

Also during the 1978 testing, water hammer was experienced at some control value positions with all liquid inlet feed. The inlet port configuration was subsequently changed to eliminate this problem.

In addition, during the spring testing, it was determined that there was one major source of noise, the alternator cooling fan. In an attempt to attenuate the noise, a quieter fan was installed, shrouded and lined with a sound absorbent material, and ducted away from direct ear contact.

With resumption of well flow by Phillips Petroleum Co., in the spring of 1979, and mid July completion of the plant repair, efforts were directed to the evaluation equipment re-installation, calibration, and general test site preparation. Equipment calibration and site preparations were hindered somewhat by a well blow-out in June 1979, which deposited salts and scale over the entire test site, causing numerous electrical problems.

Checkout of the fresh water system revealed that the steam condensate contained large amounts of iron carbonate, which precipitated probably as siderite. Various methods were attempted to solve this problem. The solution involved changing the design, to first aerate and mix the hot condensate with bentonite and then hold the mixture in a large tank where the bentonite and newly formed iron oxide would settle out. The resulting water was then filtered to 25 microns and fed to the seal metering pump.

Plant operation for testing commenced on August 29, 1979. As testing continued, it became apparent that naturally formed mineral depositions would not close the clearances internal to the prime mover. The rate of deposition was too slow to close these clearances in the time allowed for testing. Recognizing the importance of internal clearances to prime mover performance, an

attempt was made to chemically force mineral deposition to occur at an accelerated rate.

The method used to force mineral deposition to occur involved the injection of a calcium chloride solution directly upstream of the prime mover inlet. The necessary equipment involved mixing tanks for the solution, a metering pump, and an injection line to the prime mover inlet. Various combinations of concentration and flow rates were attempted with some success. However, the resulting calcium carbonate deposition that did occur deposited preferentially in some areas and not others, and continally broke off in large scales. The attempt to force mineral deposition to occur was subsequently terminated and attention given to other aspects of the evaluation.

One incident did occur, however, that demonstrated the need for a jacking motor to slowly rotate the plant immediately after stopping and before starting. Upon stopping the plant after a test run, during which a particularly concentrated solution was injected, the rotors became locked as the housing was allowed to cool to ambient temperatures. In order to free the rotors, it was necessary to block the exhaust port and fill the housing with a mild solution of hydrochloric acid and metal pickling inhibitor. After approximately 24 hours of scaking, the rotors became free and testing was continued. A jacking motor has subsequently been installed and appears to have solved this problem.

During continued testing, water build-up was noticed in the main lube oil reservoir. Inspection revealed that flush water was migrating back across the shaft seals into the bearing areas, and

to the oil reservoir at a rate of approximately 100 cc/min. This leakage was recognized as a seal short-coming and that the water would have to be periodically removed at the reservoir. For the short term and continuation of testing, bleed steam was used to dry the reservoir during periods of plant shut down. For the longer term a water/oil separating centrifuge was ordered for continuous water removal.

Concurrently, with the test activities in Utah, many visitors observed the plant in operation. During one visit, a group of foreigners, some of whom were involved in geothermal activities in their respective countries, toured the test site. They were impressed with the plant operation and test activities. Their interest led to an International Energy Agency (IEA) agreement, whereby the Power System and support test equipment would travel abroad for demonstration purposes. First on the demonstration schedule is Mexico, where the plant would be operated in the geothermal field at Cerro Prieto.

Utah plant operation and testing was terminated on November 14, 1979. Post calibration, packing, and site clean-up followed, with loading and shipment to Cerro Prieto, Mexico, on December 1, 1979.

The support activities in Utah involved a time period of 24 months from plant delivery on December 4, 1977, through shipment to Mexico on December 1, 1979. Total cost for Hydrothermal Power Co. efforts during this time period was \$530,927.

CONCLUSIONS

*s a result of the reported effort, we conclude:

- Problems associated with the initial plant operation are considered incidental and should be viewed as a normal debugging process for new equipment.
- 2. Varied geothermal well production characteristics put a large demand on the governor system. Control needs to be maintained over a wide range of inlet pressures, flows, and electrical loads. Design improvements to the governor system should satisfy these control needs.
- 3. That substantially all of the conclusions from the testing of the 62.5 KVA Prototype Power System are confirmed.
 In particular, the following conclusions were verified.
 - A. The helical screw expander is a useful, efficient, total flow prime mover;
 - B. The scaling or mineral deposits reduces leakage, between rotor-to-rotor and rotor-to-case, resulting in a substantial increase in machine efficiency.
- 4. That internal inspection of the prime mover has revealed nothing to prevent long term maintenance free operation.
- 5. The nature of the equipment, including the fault and safety shut down system, points to a Power System capable of extended periods of continuous, unattended operation.

- 6. That a Geothermal Power System could be built from a standard set of materials, adaptable to a large variety of geothermal wells and fields, and developing mechanical efficiencies greater than 70%.
- 7. That adoption of the recommended modifications would enhance the efficiency and overall attractiveness of the HPC Power System to the Geothermal Industry.
- 8. Test results have shown that the power conversion system does have an application for power recovery from geothermal brines having an extremely broad range of qualities.
- 9. The prime mover can be characterized as having a weight to power ratio somewhere between turbines and reciprocating prime movers. For example, with an installed prime mover weight of 100 tons, a diesel would produce 12 MW, a helical screw 30 MW, and a steam turbine 200 MW. This will limit the single shaft power output from a helical screw to about 50 MW utilizing existing heavy industry. This size may be increased by utilizing fabricated hollow rotors. An attractive size appears to be approximately 5 MW where the entire power plant can still be maintained easily transportable on skids and located near the wellhead.

RECOMMENDATIONS

The following recommendations are based upon operating experience. If adopted, they should result in reduced maintenance and simpler future operation.

We recommend:

- a H₂S removal system be installed in all electrical enclosures;
- a longer and wider main skid-pad for easier equipment access for servicing and maintenance;
- 3. that the safety shut-down electrical system be isolated in its own enclosure;
- 4. that the hydraulic actuator to the automatic stop-gate valve be located in a vertical position;
- 5. that the hydraulic actuator of the automatic stop-gate valve have an adjustable stroke cushion to reduce mechanical stresses on the main drive train during fault shut-down;
- 6. that the inlet pipe to the prime mover be welded to the main skid pad to reduce stresses to the prime mover feet, which could lead to misalignment;
- 7. that provisions be built into the lube oil console for additional cooling capacity when the plant is operated in hot desert environments;
- 8. that additional inspection ports be built into the prime mover housing;

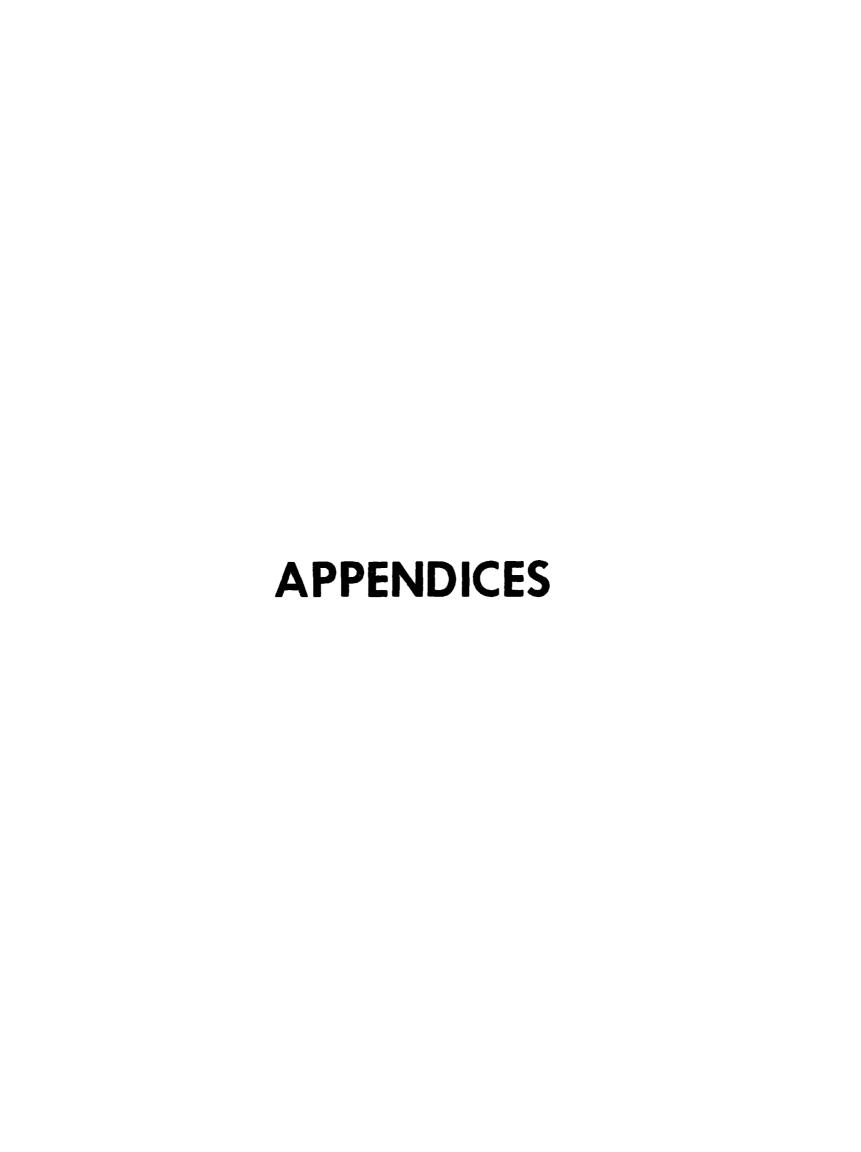
- 9. improvements be made to the governor control system to allow stable plant operation at various inlet pressures and electrical loads;
- 10. a larger lube oil reservoir capacity to accommodate of loss due to nominal shaft seal leakage;
- 11. that the manual start hand pump be changed to electrical drive;
- 12. that an event recording system be installed to monitor the plant and record the failure sequence in a fault shutdown;
- 13. that additional testing be done at different speeds, and with various field parameters;
- 14. that an HPC Power Conversion System, with a nominal capacity of 5 MW be constructed, incorporating the above design changes.

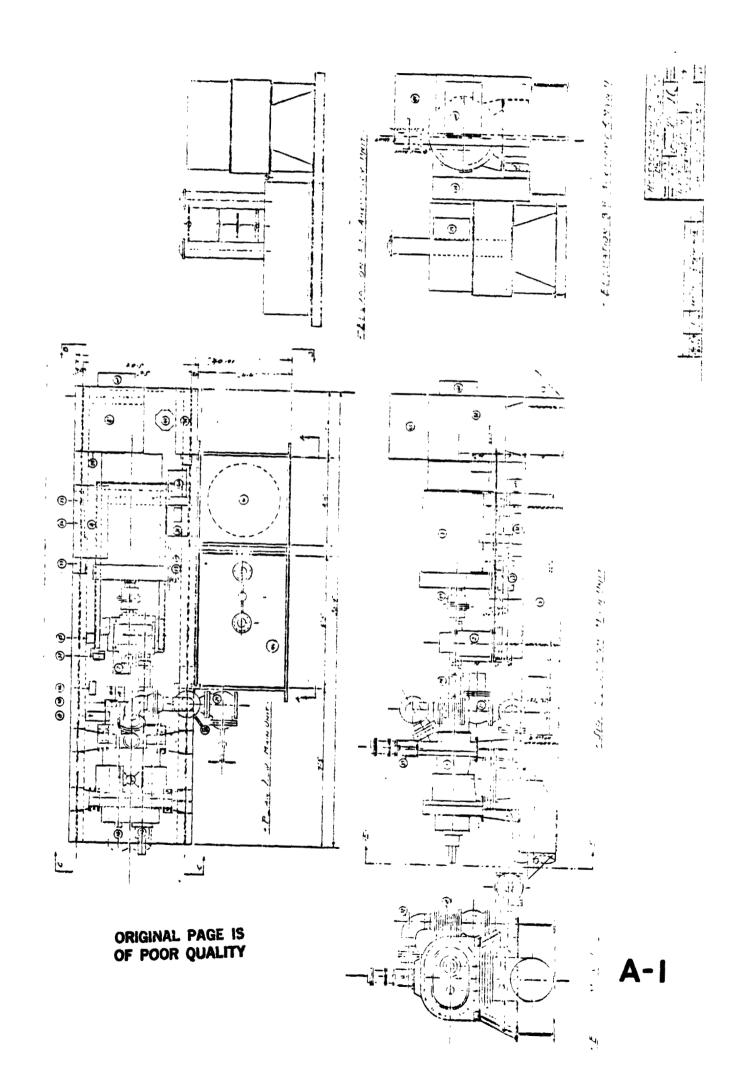
NEW TECHNOLOGY

Prior to the issuance of the subject contract, Hydrothermal Power Co., Ltd. (HPC), had developed New Technology through extensive research, resulting in patents, know-how, and proprietory rights. The research culminated in the successful operation of a prototype 62.5 KVA Power System.

Following the execution of the subject contract, HPC petitioned the U.S. Department of Energy for and received an "Advance Waiver" on New Technology developed during the performance of the contract.

No reportable items of New Technology were identified or developed during the fulfillment of the contract terms.





DESCRIPTIVE SPECIFICATION

for

GEOTHERMAL POWER CONVERSION SYSTEM

supplied by

HYDROTHERMAL POWER CO., LTD.

Pasadena, California

May 9, 1980

The Geothermal Power Conversion System consists of a Lysholm type expander with sixteen and one-half (16.5) inch diameter rotors, a speed reducer and an alternator, complete with all necessary auxiliary equipment and accessories required for use as a geothermal wellhead electrical generating plant. The drive train is a skid mounted, factory assembled unit, susceptible of transport without dismantlement. Heavy tarpaulins are provided for protection of the System during shipment or site storage. The Contractor's predictions of System performance are set forth in Appendices 1 and 2 herewith. The System includes the following assemblies, sub-assemblies and components:

I

Main Drive Train

The main drive train is mounted and aligned on a structural steel base pad or frame. The basic envelope is 6 ft. in width, 8 ft. 1" in height, and 25 ft. in length; the weight is approximately 25,000 lbs. The main drive train is exposed for ease of interfacing with process piping, lubrication oil console, and electrical switchgear. The equipment is designed for outdoor, unattended operation for extended periods. The main drive train consists of the following sub-assemblies:

(Prime Mover)

The prime mover is a Lysholm-type machine designed for operation as a high enthalpy brine expander having the following features:

1. A fabricated steel housing with porting to provide for a variable volume ratio. The housing incorporates a gate-type governing valve that controls this variable volume ratio. The inlet port is an 8-inch. 300 lb., ANSI raised-face flange. The maximum allowable operating condition is 625 psig at 500° F.

- 2. The low-pressure end is of stainless steel with a 24-inch, 150 lb., ANSI raised-faced flange.
- 3. The shaft seal assemblies consist of a combination of segmented carbon seals, floating ring seals, and labrinth seals. Oil is maintained behind the segmented carbon seals at a pressure slightly higher than the flush water pressure to prevent water intrusion into the oil system.
- 4. Radial bearings are pressure-lubricated, tilt-pad type sized for moderate to low specific bearing pressure. Thrust bearings are large, sturdy, self-equalizing type of conservative design for long life. One hundred ohm platinum resistance temperature detectors are provided on all bearings.
- 5. Two 1 1/4-inch, threaded, plugged, inspection holes are provided in the rotor bores with provisions for measuring rotor wear.
- 6. Rotors are machined from solid, one-piece forgings to provide the maximum practical bending strength.
- 7. Rotor construction is suitable for 100 psi pressure differentials at rotor speeds up to 5,000 RPM.
- 8. Hard-surfaced rotor tips and end faces are provided.
- 9. A jacking motor is provided to slowly rotate the prime mover during periods of startup and shutdown.

The prime mover housing is hydrostatically tested according to the ASME Boiler and Pressure Vessel Code. The inlet and high pressure regions are tested to meet or exceed a 300 lb. ANSI rating. The exhaust and low pressure regions are tested to meet or exceed a 150 lb. ANSI rating.

(Speed Raducer)

A suitable speed reducer is provided and is flexibly coupled to the prime mover and to the alternator. The speed reducer is a parallel shaft horizontal offset design having sleeve type berrings. Lubrication is provided from the main lubrication console. The high and low speed couplings are self-aligning gear type with sealed grease lubrication. The low speed coupling is of the shear-pin type. The couplings are designed to operate for 20,000 hours before recommended disassembly for an alignment check and re-lubrication. The speed reducer is generously sized for an extended life of greater than ten years before overhaul. Gear sets for three gear ratios, 5000/1800, 4000/1800 and 3000/1800 rpm (approx.) are supplied with the gearbox.

(Alternator)

The alternator is a continuous duty 1000 KW, 1250 RVA, 0.8 p.f., 1800 rpm., 3 phase, 60 HZ, 480/277 volt, 4 lead, 2 bearing, drip proof, enclosed machine suitable for operation in a desert environment, and having a directly connected brushless excitor and a solid state voltage regulator. The alternator bearings are of the antifriction type with double shields and are lubricated at the factory. The alternator bearing is of a design capable of ten years of continuous operation. Two 100 ohm platinum resistance temperature detectors are installed in each phase of the windings to make possible a continuous indication of alternator temperature. A 100 ohm platinum resistance temperature detector is installed on each bearing. To reduce noise, the cooling fan is ducted and shrouded away from direct ear contact.

II

Oil System

The oil system provides bearing lubrication as well as cooling for the prime mover and the speed reducer. It also provides oil for the shaft seal needs and the hydraulic needs for the speed governor and safety shutoff mechanisms. The oil system also includes a heat exchanger and other provisions necessary to maintain the prime mover and the speed reducer at proper operating temperatures by transfer of heat from the oil to the surrounding atmosphere. A fully automatic greasing system is provided for the lubrication of all critical surfaces or bearings within the brine inlet and governor control valve. The oil system includes the following subassemblies and components:

(Lubrication Console)

- 300-gallon reservoir with sight gauge, breatner, and fill cap
- 2. Duplex filter and transfer valve
- 3. Forced draft oil-to-air heat exchanger
- 4. Oil pump directly connected to speed reducer at 1800 rpm
- 5. All associated piping, temperature and pressure regulators, gauges, and switches

(Shaft Seals)

- 1. Booster oil pump, filter, accumulator and regulators to shaft seals
- 2. A flush water pump, duplex filter with transfer valve, and flow meters to feed one GPM of suitable flush water to each shaft seal

 A water-oil centrifuge to remove water from the seal oil discharge

(Auxiliary Functions)

- Sufficient oil capacity and accessories are provided to assure proper operation of the governor and its hydraulic amplifier
- Sufficient oil capacity and accessories including an accumulator are provided for hydraulic operation of the automatic gate shutoff valve.

III

System Control (Speed Governor System)

The governor system has the following features and characteristics:

- 1. The governor is a mechanical flyball-type, flexible spline connected to the female rotor of the prime mover.
- 2. The governor output is amplified through a hydraulic servo mechanism for operation of the governing valve located in the prime mover inlet port.
- 3. There is a means for adjustment of the governor with provision for remote control from the electrical control box.
- 4. The governor control mechanism provides means for either isochronous control or droop control at the election of the operator. The accuracy of control in either case is within plus or minus one quarter (1/4) of 1% of the speed set or selected by the operator.

(Automatic Gate Shutoff Valve)

The automatic gate shutoff valve is wired for automatic fail-safe operation wheneve there is a dropout of the electrical signal required to hold it open. The generator output breaker trips open also with a dropout of the electrical signal due to underspeed.

Provisions are made for actuation of the automatic shutoff valve in consequence of any one or more of the following conditions, any one of which will trip and fully close the automatic gate shutoff value within fifteen (15) seconds:

- 1. Underspeed
- 2. Oil supply overtemperature
- 3. Oil supply underpressure
- 4. Shaft seal low differential pressure
- 5. Shaft seal low flush water flow
- 6. Excessive vibration
- 7. Actuation of manual stop switch

Page 4 of 9

Provisions are also made for actuation of the automatic shutoff valve in consequence of any one or more of the following conditions, any one of which will trip and fully close the automatic stop gate valve within one (1) second:

- 1. Overspeed
- 2. Actuation of manual emergency stop switch.

Relays are provided for remote actuation of both the stop and emergency stop switches.

IV

Electrical Systems

The Geothermal Power Conversion System is designed for starting without any external electrical power source. Batteries are provided to energize the safety shutoff circuit during startup and during normal operation. During operation, all necessary electrical energy, including that for battery charging, is provided by the System itself. All of the electrical lines, connections and contacts are protected from the corrosive salts and gases prevalent in geothermal environments. Protection for all instrumentation and signal wires is provided by conduit, gutter or tray as appropriate for the protection and isolation of such circuits within the perimeter of the Geothermal Power Conversion System. The electrical system includes the following subassemblies and components:

(Alternator Control and Protection)

The alternator is provided with all necessary or required protective and control devices requisite for safe operation. Accordingly, an output circuit breaker complete with solid state protective devices for circuit fault, ground fault and thermal overload conditions is provided for the main load. The output circuit breaker has a 120V AC shunt trip coil. In addition, a 40C amp., 480 V., 3 phase breaker panel is provided for possible power needs at the geothermal plant site. A separate 120 volt output breaker is provided for all inhouse usage.

The alternator is provided with a control box or console having provisions for the measurement of alternator frequency, voltage, current, power output, and kilowatt hours. A current transducer and a power transducer each provide 4 to 20 MA output. Indicating meters are provided within the control box. Means are also provided there for the convenient connection for external recording of ampelage and voltage. The control box also contains an elapsed time meter, necessary relays and timers, as well as the voltage regulator and a remote governor control switch. A 10 KVA single-phase transformer with 110/240 volt output together with output circuit breakers for the control of all electrical energy

(station power) used for operation of the System is also provided. The arrangement of the control box panel is generally in accord with JPL Drawing No. SE/60-0 that appears in the JPL ELECTRICAL STANDARDS published in June 1975 by the JPL Facilities and Engineering Construction Office.

(Remote Monitoring)

A terminal box containing a terminal strip is provided to facilitate the remote monitoring of the following:

- 1. Alarm and sensor contacts giving indications of improper speeds, pressures, temperatures or vibrations
- 2. Remote circuit breaker trip mechanism
- Station power (120/240 volt)
- 4. Temperature sensors
- 5. Bearing load sensors
- 6. Amperage transducer
- 7. KW transducer
- 8. KWH pulse
- 9. Voltage
- 10. Frequency
- 11. 24 Volt DC Supply.

(Remote Control)

A terminal box containing a terminal strip is also provided to facilitate the remote control of the following:

- 1. Voltage
- 2. Frequency
- 3. Normal stop
- 4. Emergency stop.

Page 6 of 9

Inlet Piping

The System includes adequate means for support and flexible coupling of the upstream piping so as to minimize any mechanical loading of the prime mover. The inlet piping is capable of safe handling of geothermal fluids at pressures up to 625 psig and temperatures up to 500°F. All inlet piping is hydrostatically tested to the ASME Boiler and Pressure Vessel Code to meet or exceed a 300 lb. ANSI rating. The inlet piping of the System includes the following components:

- 1. 8-inch, 300 lb. ASA gate start and stop valve
- 2. 8-inch, 300 lb. ASA automtic gate stop valve, pneumatically-hydraulically actuated
- Flex-coupling at prime mover inlet, 8-inch, 300 lb. ASA rating
- 4. Burst-type bypass plus relief valve.

VI

Drawings

The Geothermal Power Conversion System is furnished in conformity with the following drawings as prepared by the Hydrothermal Power Co., Ltd.

Drawing Number	Issue Date
1. B-13	As revised 1-18-78
2. B-14	As revised 5-9-80
3. B-20	As revised 5-11-80

APPENDIX 1

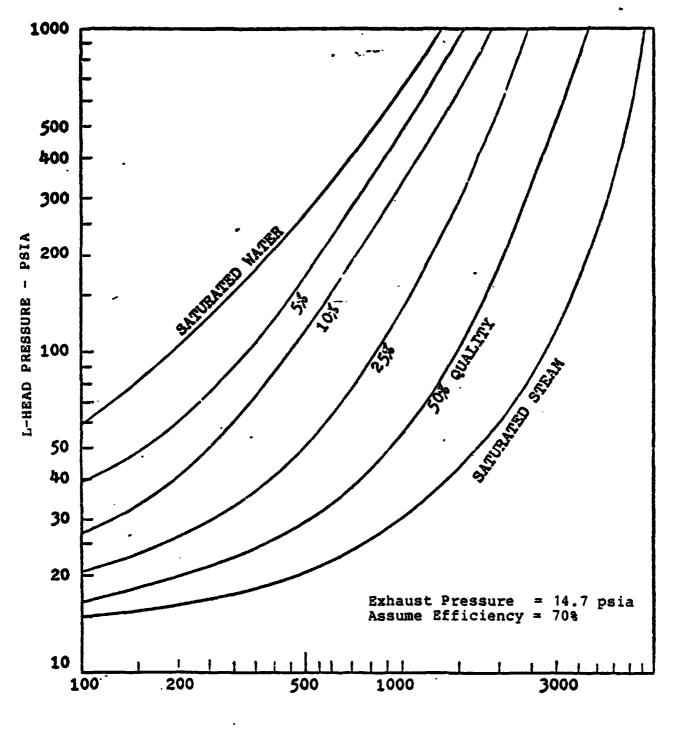
HYDROTHERMAL POWER SYSTEM PERFORMANCE

1250 KVA PLANT

	CASE I	CASE II
SIZE	16.5" Rotor diameter 25" Rotor length	same
POWER	1000 KW Prime Mover Shaft Output	same
RPM	4000; = 288 ft/sec tip velocity	same
FLOW RATE	135,000 lb/hr.	85,000 lb/hr.
ENTHALPY	424 Btu/lb. inlet	same
TEMPERATURE	444°F	same
PRESSURE	400 PSIA inlet 14.7 PSIA exhaust	400 PSIA Inlet 3 PSIA exhaust
QUALITY	0 at inlet	same
EXPANSION RATIO	347/1	1500/1
PRIME MOVER EFF.	70% of isentropic	65% of isentropic
SPECIFIC CONS.	135 lb/KWhr.	85 lb/KWhr.

NOTE: Assume Keenan and Keys Thermodynamic Properties of Water, 1969 edition.





SPECIFIC POWER OUTPUT KW 105 1b/hr

HYDROTHERMAL POWER SYSTEM PRIME MOVER PERFORMANCE

"YDROTHERMAL POWER CO., LTD.

2051 Woodlyn food • Posedene, California 91104 (213) 798-1005 27032 Via Calledo • Mission Viejo, California 92473 • (714) 837-3081

REQUEST FOR QUOTATION

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Ľ.	CERTIFIED UNDER DMS REG. 1 TAXABLE NO X YES CALIF. RESALE NO. SR AP 17-668216						
Γ .	PRIORITY RATING DO-A2						

AUTOMATIC GATE VALVE

(1) One 8" 300# ASA flanged, hydraulically actuated, Gate Valve. Body, bonnet, and yoke of ASTM A216 grade WCB; seats and wedges of ASTM 182-F6 and with Stellite No. 6 coaring; and the stem of ASTM 182-F9. The valve shall be controlled by two input signals either one of which will automatically close the gate valve upon signal loss. Both signals shall be 12 VDC with 2 amp. maximum current. Signal loss from one of the inputs shall close the gate valve within one second, and a signal loss from the other input shall close the gate valve in approximately 15 seconds.

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COVERNMENT SUBCONTRACT

Any Purchase Order issued by HPC as a result of your quotation will constitute a subcontract under Contract MAS7-100 between the United States of America and the

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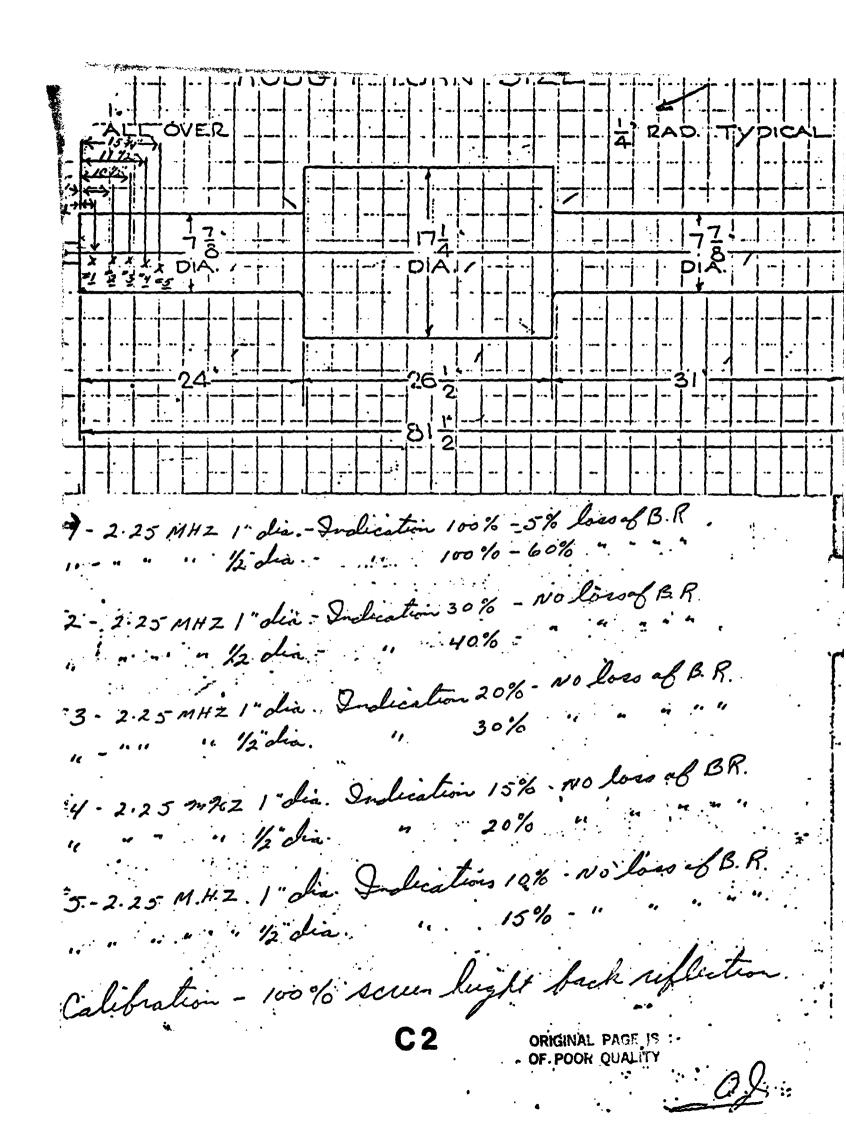
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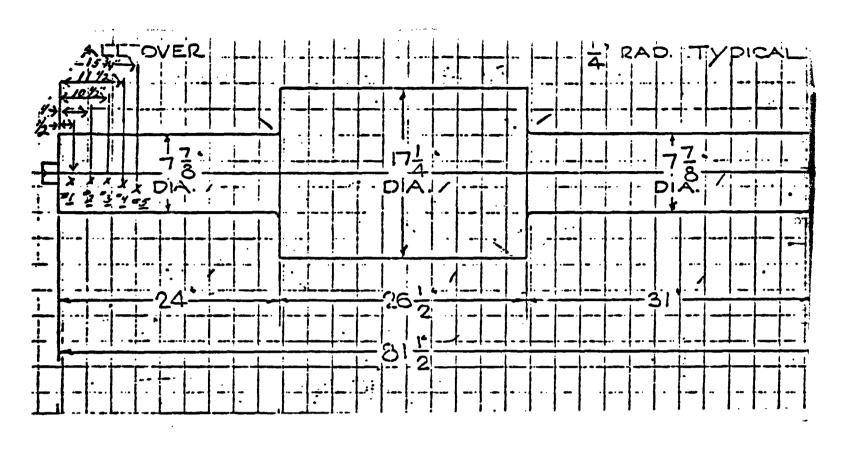
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Smirring United

A FINITE ST. SOILS, CLX

Phone: 773-4040

No. 4657

HIP TO:	SYAMEX FORGE DIE CO MONTERY PARK CALIF		Date 11/5/ Order No. 76	76 M-/-C-i H
HARGE TO:	HYDROTHERMAL POWER CO LTD 27032 VIA CALLADO MISSION VIEJO CALIF 92675	35	F.O.B	
V QUANT T	MATER'AL	WEIGHT	PRICE	ERTENSION
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	269/302 BHN, 28/32 RC FINISHED SIZES			
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Date Delivered	Jack Behnens (3-P)	-5/-	are fam.	

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A Finkl & Sons Cc.;

METALLURGICAL REPORT

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ULTRASONIC REPORT

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2 cop./C.A.R.

DATE 11-2.76

CUSTOMER FINEL (CAL.)

CUSTOMER ORDER NO.9/24/76/01

DESCRIPTION /0 X 32.5 X 3 P"

SHOP ORDER NO. / 5645

HEAT NO. 160576

- QUANTITY TESTED /pc

SONIC UNIT SPERRY UN 715

SEARCH UNIT SPERRY 2.25 MHz - 1.125 Dia. Qtz

COUPLANT 30 OIL

TEST BAR-\$/64" F.B. HOLE

TEST BAR.

SENSITIVITY ADJUSTMENT:

- SCAN FACE - 4/64" F.B. HOLE -2 pip (Swp/pk) on SCOPE

RESULTS:

No indication found of loss in a full recome book reflection did not exceed 10%

Q. C. Manager

DORK CTEEL PROBUBATION	MILL OF THE SURFICE TO THE PROPERTY OF THE PRO	1821 : W TANK THE	M : HITSUBISHI INTERNATIONAL CO. PORTLAND MIE OF BRIF : NOV.	SHETTA : MITSUBISHI CORPORALION SHETTE CONTROL STATES 120 1.	Repression that Tensilu Tens 2 Volume Chemical Companies on		2	34257501 32300 67300640 128 670103 31 3 913103	132700 65600620 138 664	32900 85500650 129 6	. 33100 87500640 138 465100	33071801 32704 85506630									·☐────────────────────────────────────		WE HERENY CERTIFY THAT THE MATERIAL DESCRIBED HEREIN HAS BREW	1977	Hange of Action Hand			PAG QUA	
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66020

76-M-1-C-2A

CUSTOMER ORDER NEMBER SHUTHING

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Producers of Standan Stud. This Price Office and Titernium.

THORNDALE, PA 19372

G.O.GARREOM La

ENERGINE STREET OF THE WARRY

10/21/76 5. SXY TEST. REPORT

76-M-1-C-2A

TYPE AND SPECIFICATIONS

HYDROTHERMAL POWER CO LTD 25721 DBRERO UNIT B MISSION VIEJO, CA 92675

304 ASME SA-240, WINTER 1975 HRAP

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5.2500 GA. BKETCH A-7	656673-1	11	38000	83500	8	71	157	<u>-</u> -	
Ultrasonic Report Attached.									
D5									

NI 8.83 SI CR .49 18.50 .050 1.44 .019 .012 656673-1

AND THE STATE OF T

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Sworn to and subscribed before me this...

10/21/76

Producers of Standard Start.

Michel Allery and Titanum
THORNOALE 84 19372

REFER TO THE MILENE & 66020

569 LA	2 S 76-M-1-C-2A			76-M-1-C-2A	
ACTUAL ROUTING	KAG/WEST CARLOADING PREFAID				
	SOLD TO			SHIP TO	
Γ	HYDROTHERMAL POWER CO LTD	7	Γ	A. Finkl and Son C/O Bud Finkl	7.7
L	25721 OBRERO UNIT B MISSION VIEJO, CA 92675		L	10735 Sessier Street Southgate, CA.	١
-	MEAN	DSPEC	11 40		
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1 5.2500 GA. SNETCH A-7

F/C PERIPHERY & HOLES
TOL. PERIPHERY + 1/4 - .000
HOLES + .000 - 1/4

**** CHEMICAL ANALYSIS ****

ITEM- 1 QTY- 1 HEAT- 556673-1 C MN F S SI CR NI .060 1.44 .019 .012 .49 18.50 8.83

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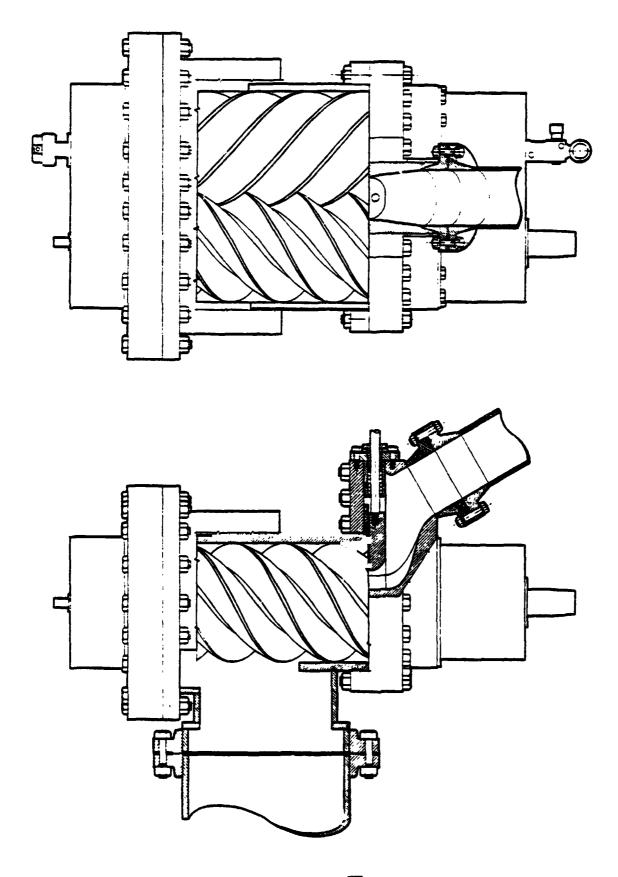
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1990

GUC 66620 CUSTOMER HYDROTHERMAL POWER COMPANY P.O.# 76-M-1-C-ZA DATE 10/15/76 TYPE 304 COND. HRAP FORM PATTERN (SKETCH)	(X) LONGI TUDINAL; PER ASTM - A435	() SHEAR :	SCAN SPEED: 6"/Sec. Max OVERLAP: 10%Min. METHOD CONTACT COUPLANT WATER & DETERGENT	EQUIPMENT SPERRY UM 775 PULSER 10-S #2 SCANNING 100% ONE MAJOR SURFACE		SIZE SIZE FREQ. SEMS. SWEEPBR	1 656673-1 5.250 Ga. SKETCH AERQ STR 1"Ø 2.25 X1-4 .5 2 N/A N/A		D7			RESULTS: THE ABOVE MATERIAL WAS TESTED BY THE INSPECTOR(S) AND LONGITUDINAL WAVE METHOD AND FOUND TO BE ACCEPTABLE QUALIFIED: SNETC-TAXXEVEL II (X)MIL-STD-271E	CUSTOMER REP.
60C	U. 7		SCAN	EOUI	PAR	1 TEM	_					RESU LONG TO T	



HYDROTHERMAL POWER CO., LID.

QUALITY CONTROL PROCEDURE

In order to assure the absolute conformance of incoming materials, purchased parts, machining or processing of materials and purchased parts, each such incoming item received by HPC secured for integration into the HPC Power Conversion System, is to be checked against the purchase order and purchase order drawing as to both quantity and quality.

A record will be maintained by HPC showing the results of checking, inspection, and measurement upon receipt of incoming materials, purchased parts, machining or processing of materials and purchased parts.

Such record shall be in the following form:

Α,	PART NO. or PURCHASE ORDER NO.
В.	DESCRIPTION of PART or TASK
C.	DRAWING NO.
D.	(1) DATE of PURCHASE ORDER
	(2) DATL of RECEIPT BY HPC
	(3) DATE of INSPECTION
E,	MANUFACTURER, VENDOR OF SUPPLIER
7.	CRITICAL MEASUREMENTS TAKEN BY:
G.	CPITICAL MASUREMENTS TAKEN DATE:
Ħ,	CRITICAL MEASUREMENTS RECORDED ON SHOP DESMITING OF COPY OF PURCHASE ORDER (1)BY:
	(2)DATE:
1.	ACCEPTANCE DATE
5,	COMMENTS

F

Brief Summary of Torsional Frequency Analysis

A lumped-mass mas; model was constructed for the entire system. This model consists of five "inertias" (actually moments of inertia) which represent respectively:

Female & Male Rotors & Shafting of the Compressor

The First Coupling

The Speed Reducer

The Second Coupling

The Alternator (Fan, Rotor & Exciter)

These five inertias are coupled by four uniform shafts. The numerical values of the inertias and of the torsional rigidities of the shafts were determined from values on the blueprints or were calculated from the physical dimensions provided. All calculations were made with reference to the Male Rotor Axis.

The analysis of the Free-free torsional vibrations of the system is accordingly reduced to an eigenvalue problem. The eigenvalues are found to be the roots of a tenth-order algebraic equation in the circular frequency w*. One root, as expected, is W-O, which corresponds to a rigid body rotation of the entire system. Thus the determination of the eigenvalues amounts to the determination of the roots of a fourth order equation in Wⁿ. The four roots correspond to the frequencies n (hz) of the four principal modes of torsional vibration of the system which have one, two, three or four rodes corresponding to the increasing numerical value of the frequency. Usually the lower frequencies are those of particular interest in practice. The natural frequencies of the higher order modes are generally beyond the operating frequencies of a system.

G₁

*The tenth order equation can be treated as a fith order equation because only even powers of W occur in it.

The rour rrequencies "1 (1 = 1,...4) were determined for three different speed ratios for the five mass system. The results are as follows:

Case I; Speed Ratio 1800/3000

 $n_1 = 64 \text{ hz}$

 $n_2 = 189 \text{ hz}$

ⁿ3 = 315 hz

 $^{n}4 = 609 \text{ hz}$

Case II: Speed Ratio 1800/4000

 $n_1 = 52 \text{ hz}$

 $n_2 = 191 \text{ hz}$

 $n_3 = 294 \text{ hz}$

n4 = 574 hz

Case III; Speed Ratio 1800/5000

 $n_1 = 47 \text{ hz}$

 $n_2 = 209 \text{ hz}$

 $n_3 = 308 \text{ hz}$

 $^{n}4 = 629 \text{ hz}$

These values have been determined subject to certain approximations which should be noted:

- i) Continuous mass distributions have been lumped
- ii) Continuous parameter distributions e.g. torsional rigidities have been lumped
- iii) Gear assembly is assumed to be rigid. Gear & tooth flexibility is neglected and gear backlash is ignored

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- iv) Frictional energy dissapation e.g. in flexible couplings is considered to be neglegible throughout the system
- v) Flexural vibrations have not been considered

A lengthier and more detailed analysis would be needed to include the effects of these approximations.

keferences:

Two basic works of reference are "Practical Solution of Torsional Vibration Problems" by W. K. Wilson, Wiley, New York, 1956 (Two volumes) and "Handbook on Torsional Vibrations" by E. J. Nestorides, Cambridge University Press, 1958.



philadelphia gear corporation

November 15, 1977

Hydrothermal Power Company, Ltd.

25721 Obrero, Unit B

Mission Viejo, California 92675

Attention: Mr. J.A. Sprankle

Subject: Your P.O. #76-M-4

Our Order #489254 Efficiency curves

Gentlemen:

To confirm our meeting of 11-9-77, the efficiency curves that were delivered to you on 10-25-77 were derived in a similar fashion a outlined to you in a July 21, 1977 letter from our Michael Hardi in. The empirical data on the above order has indicated about an 8% error in the calculated constant that we used in our heat-balanced equation. This error, in all probability, is caused by aeration of the oil. The empirical formula accounts for this and includes radiant heat losses as well

Hopefully, this is the information that Dr. McKay is looking for. Please advise us if there is anything else we can do to bring this matter quickly to a close.

Very truly yours,

PHILADELPHIA GEAR CORPORATION

Mark M. Alter

Sales Representative

MMA/fj

cc: Dr. R.A. McKay - Jet Propulsion

cc: John L. Gillaspy - Anaheim

Parl 17 sew fin 1-213-577 0506

MARK M. ALTER Sales Representative

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26CO EAST MIRALOMA WAY ANAHEIM, CALIFORNIA 92806 (* :4) 830-7800



philadelphia gear corporation

July 21, 1977

Hydrothermal Power Co., Ltd. 2051 Woodlyn Road Fasadena, California 91104

Attention: Mr. J. A. Sprankle,

Business Manager

Reference: Your P.O. #76-M-4

Our Order #489254

Your Letters of 7/12/77 and 6/14/77

Gentlemen:

I appreciate your concern in receiving the required efficiency data as well as your demonstration of good faith with the trustee account. As you know, we have submitted one set of efficiency data but unfortunately, the inlet oil temperature has been changed rendering this data unusable for your purposes. Also, you must realize that the calculation tools available today are not sophisticated enough to guarantee the 1/2 of 1% maximum error you have requested.

A telephone conversation between Dr. McKay and myself indicated that an explanation of our testing/calculating heat loss method may suffice in satisfying this requirement.

I have attached three sheets covering the derivation of our heat balance equation and the particular lubricant used at our test stands. As you will note, empirical data has indicated about an 8% error in the calculated constant. This error, in all probability, is caused by aeration of the oil. The emperical formula accounts for this and includes radiant heat losses as well.

2

Hydrothermai Power Co., Ltd. Mr. J. A. Sprankle July 21, 1977

If possible, Dr. McKay should run both loaded and unloaded tests using a torque cell and tachometer to verify the accuracy of our conscant under his test stand conditions. Once this is established, the accuracy he requires for his testing should be attainable.

I hope this data will suit your requirements. If there are any questions, please contact me.

Very truly yours,

PHILADELPHIA GEAR CORPORATION

Michael J. Hardiman, Manager Special Products Division

enc.

cc:

Dr. R. A. McKay/Calif. Institute Tech.

- J. Gillaspy/P.G.C., Anaheim, Calif
- J. Pooler/P.G.C., King of Prussia, Pa.
- R. Meyers/P.G.C., King of Prussia, Pa.

DERIVATION OF HEAT BALANCE EQUATION

ALD: 462140
TYPE OF LOBRICANT: MOBIL DIE LIGHT (SPEC. SWEET ATTACHED)

DIMENSIONALLY

MOBIL REPORTS THE FOLLOWING WITH . REFERENCE TO DIE LIGHT

WEIGHT PER GALLON = 7.25/ LB SPECIFIC NEAT = .48/ __BTU_ pr-0F

INSERTION INTO THE DIMENSIONAL EQUATION YIELDS

HP = (GPM)(7.251)(481)(AT)
42.45

COLLECTING ALL CONSTANTS

By NONITORING SETERAL UNITS ON TEST USING
A TORQUE CELL TO NEASURE INDUT TORQUE AND
AN ELECTRONIC TACHOMETER TO MONITOR SPEED
THE CONSTANT .0822 WAS EMPIRICALLY FOUND
TO BE EXCESSIVE. USING A BROAD RANGE
OF SIZES AND OR TYPE OF UNIT THE CONSTANT
.0762 WAS FOUND TO YIELD MORE ACCURATE
RESULTS. THIS ACCOUNTS FOR CHURNING, BERATION, ETC.

EMPIRICALLY H4 $HP = .0762(GPM)(\Delta T)$

Motest 5 RE-20 Series

ORIGINAL PAGE IS OF POOR QUALITY Model Elle & F 46



Mobil D. T. E.® 20 Series Hydraulic Oils

The Mobil D.T.E. 20 series of high quality oils has been developed specifically to satisfy the requirements of hydraulic systems using the newer, high-pressure, high-output pumps. The large growth in hydraulic operation of systems on mobile equipment has resulted in the development of pumps that are smaller, yet deliver greater volumes of fluid at higher pressures than were thought practicable a few years ago. Since response time is improved when a smaller volume of fluid at higher pressure is used, high pressure pumps are also being applied increasingly in hydraulic systems of machine tools and other industrial applications. Pump vanes or pistons, control valves, and linear and rotary actuators of hydraulic systems all operate with boundary or mixed film lubrication so that wear protection must be provided by thin oil films. As pressures and operating speeds are increased, the loading on these thin films is increased, and the fluid must provide greatly enhanced antiwear or film strength characteristics to protect against excessive wear. At the same time, oxidation and foaming resistance, demulsibility, and rust and corrosion protection must be maintained at high levels to avoid other operating problems.

PRODUCT DESCRIPTION

The Mobil D.T.E. 20 series was developed in cooperation with pump and hydraulic system component manufacturers to provide the superior antiwear and film strength characteristics necessary for the new high pressure hydraulic pumps that are coming into wide use. They are formulated from high quality. chemically stable, high VI base stocks combined with additives chosen to provide the specific properties required in hydraulic fluids. Compared to the best automotive oils, they provide superior performance characteristics including demulsibility. rust prevention, and resistance to deposit formation. and equal antiwear protection. In addition, the viscosities are chosen to accurately meet the requirements of hydraulic pump builders and coincide with the new ASTM viscosity grades. Furthermore, their functional characteristics permit a wide range of industrial applications other than in hydraulic systems.

In the development of the Mobil D.T.E. 20 series, extreme care was given to the selection of antiwear agents and rust inhibitors which will not interfere with water separating characteristics. The combination of additive components was carefully balanced with the base stocks to ensure that the final products provide the best obtainable combination of antiwear, demulsibility, oxidation resistance, rust protection and foam resistance properties. A protective barrier is provided by a thin film of oil which prevents the rusting of metal parts in the presence of small

		Mobil D.T.E. 25	Mobil D.T.E. 2
31.7		30.6	29.9
0.867		0.873	Q. 87 7
0 (—18)		0 (18)	0 (—18)
395 (202)		400 (204)	400 (204)
153		225	300 '
43		49	53
33		48.5	65
5.1		7.0	8.2
95	_	95	96
Pass	us '	Pass	Pasa
2.0	ПЭ -	2.5	3.5
0	•	0	Pess
	0.867 0 (—18) 395 (232) 153 43 33 5.1 96 Pass	0.867 0 (-18) 395 (202) 153 43 33 5.1 95 Pass 2.0 H 5	0.867 0.873 0 (-18) 0 (-18) 395 (232) 400 (204) 153 225 43 49 33 48.5 5.1 7.0 95 95 Pass Pass 2.0 H 5



amounts of water or condensed moisture from the air. They have shown superior fluid durability (resistance to deposit formation) and exceptional service performance.

TYPICAL CHARACTERISTICS

Physical and chemical characteristics of the Mobil D.T.E. 20 oils are shown in the data sheet table. Those values which are not shown as maximums or minimums are typical characteristics which may vary slightly.

APPLICATION

Mobil D.T.E. series oils are recommended for hydraulic applications in industrial. marine and mobile service. These oils are Mobil's primary recommendation for all hydraulic applications including the newer, high-pressure systems in industrial service, especially when the equipment manufacturer specifies the use of antiwear type hydraulic fluids.

Since Mobil D.T.E. 20 series oils are the primary hydraulic recommendation at all times, application consists mainly of selecting the proper grade for the particular system. Selection of the correct viscosity is based on ambient and bulk fluid temperatures, as well as the operating pressure and design characteristics of the pump and system. Mobil D.T.E. 24 is recommended frequently for small gear pumps, vane pumps and both radial and axial piston pumps. Mobil D.T.E. 26 is recommended as the oil meeting the viscosity requirements of vane pumps and gear pumps operating at high pressures or temperatures. It is also recommended for radial and axial piston pumps. Mobil D.T.E. 25 meets the viscosity requirements for many vane pumps and is an excellent product to simplify plant inventory, when a single oil is desired to replace one of 150 SUS (32 cSt) at 100 F (38 C) and another oil of 300 SUS (65 cSt) at 100 F (38 C).

Some hydraulic equipment manufacturers specify a preferred viscosity (at 100 F) for vane and axial piston pumps. Mobil D.T.E. 24 is recommended where a 150 second oil is specified; Mobil D.T.E. 25 for a 250 second oil and Mobil D.T.E. 26 for a 300 second oil. Other manufacturers base their recommendations on pump pressures. When this pressure is below 1000 psi (70 kg/cm²), Mobil D.T.E. 24 is recommended; below 1500 psi (105 kg/cm²), Mobil D.T.E. 25; and over 1500 psi (105 kg/cm²), Mobil D.T.E. 26.

Mobil D.T.E. 20 series oils are also recommended for many circulation, splash, bath and ring oiling systems supplying lubricant for the bearings and gears of industrial machinery. Their adaptability to these applications can greatly reduce inventory and lubrication costs where these oils are required for hydraulic use. They are not recommended for steam turbine nor animonia refrigeration compressor service. Where no unusually high temperatures are involved, Mobil D.T.E. 26 may be used as the lubricant in single-stage reciprocating compressors up to 80 psig (5.6 kg/cm²) or in two-stage reciprocating compressors up to 150 osig (10.5 kg/cm²) of the type normally used for producing "plant" air.

ADVANTAGES

Mobil D.T.E. 20 series oils offer the following advantages and benefits:

Outstanding antiwear performance

High resistance to oxidation degradation

Good protection against rust corrosion

Good foam resistance

Good water separation in hydraulic systems

Correct grades for hydraulic service

Worldwide availability

H6

PH ADELPHIA GEAR CORPORATION

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UNIT TEST REPORT

5/4/	777 thru	PARTIAL FINAL UNIT	Major Corrections Necessary & Rerui Accepted		ORDER NUMBER	489254
L EPARTMENT	COPIES	Size & Type	8 HS		Serial Number	121680
والمتابة والمام عداد	, ,					Note 1
Fill and FRING	1 1	<u> </u>				1800
	 	Ratio <u>Note</u>	1Reversable	No	Output Tarque	
i () LAB.				TEST C	CONDITIONS	
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1111	1					50 HP Reeves
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	1 1					
					None Vaprotec Li	
	1 1				_Oil Pressure Hot	
	1 :				Oil Inlet Temp	
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norrantal NM Axi						
SOUND LEVEL Ambie			erall SoundN	M	_ High Octave	NM Freq. NM
All occessories mounted						
NOTES, REJECTIONS	, CORRECT	IONS, ETC	* See	atta	ched data sh	eets
Note			Input Spee	_	Ratio	
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		2	4000 R	1PM	2.216:1	
		3	<u>50</u> 00 R		2.781:1	
•				- 47 ⁻		
TEST PERSONNEL			ASSEMBLER		APPRO)VAL
J.Gorden, B. B	ailey,R	.Scheler		-		Mores
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UKUER NU. 40 7 42 7-1 SERIAL NO. 12/650 UNIT TEMPERATURE DATA JIMELL SIGNED AL CLU

(Always accompany with P.G.C. Sheet No. ETL-1)

	REMARKS			WENNIK																					
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	SUMP ?	25	47	101		711	113	115	116	120	122	123													
	SOT LE	25	97	101	901	111	113	115	مااا	120	183	123													
00 FR	OOLER OUL 6 SUMP HOUSING THE OUL COLL SUMP H																								
	WATER INLET	SHO	ロディ	OFIE	ロドド	OFF	730	OFF	OFF	OFF	OFF	370													
	PRES.	52	25	37	77	25		Ų	25-	72	25	25													
	FLOW GPM	13	13	14	14	14	h)	7	15	15	16	16													
	LOAD	58,11		,		1	7.		٤	-	1	+													
1	SPEED	1300	1500.	1800	1800	180	7831	705	1840	15:20	1520	1500													
	TIME	04150		10 au	1015	1030	JE401	Coli		1130	1145			_											
					·0	יר א	ERIA SE	¥			proci		H	8					<u> </u>	\				المديدا	

CATA MUST BE ACTUAL, NOT RATED VALUES: IF NOT MEASURED, LEAVE BLANK

SHEET NO. ETL.

STARTED UNIT CHIO

DATE 5 - 116 - 77

SIGNED

SERIAL NO.

ORDER NO. 489254-1 SERIAL NO. 121680

UNIT TEMPERATURE DATA
(Always occompany with P.C.C. Shoot No. ETL- 1)

	REMARKS		- 1	הפסטור אינ מיינה ה	-																		MEET NO. 671-3
	HS V &	2.15	EUS	3110	21.0	0.15	31.0																Ī
_	3 / 3 / 3	4.0	410	20.00	613	0:35	2.0				ļ	ŀ	1										
(Label)	9																						
BEARINGS (Label)	5																						
BEA	D.T.	16	00	121	123	126	129	•					0	RIG	NA OOI	LP	AG	E IS					
	HS In 3	100	107	111	113	117	120										574						
	15 Out 2	100	106	104	107	112	114	-															
	LS LS In 8 Out 2	15	2 6	103	107	111	hii													•			
7	SNI	15	62	9	55	103	101																
,	4	62	57	10	101	111	\$11	'															
	OIL 6	42	97	101		111	113	,															
COOLER		hX	93	47	103	108	an																
	WATER	DEE	ace	956	ari-	OFI	151																
	PRES.	35	35	35	25	35	25																VALUES
	FLOW	12	13	16.	14	14	14																T RATED
	LOAD	8 P! H TEST	"	11		"	1																LEAVE I
	SPEED HAS HAS	1890	1800	1800	70/31	0001	150%																ST BE AC EASURED,
	TIME	05120	Ciuc	15.61	1015	1690	Shall																DATA KUST BE ACTUAL, NOT RATED VALUES: IF NOT MEASURED, LEAVE BLANK

H 9

PRES. WATER PS.	WATER WATER OF F	UNIT TEMPERATURE DATA (Always occompany with P.G.C. Sheet No. ETL.!)	1	OUTLET SUMP HOUSING THS HS LS LS 6/	1- 82 87 87 79 92 100 79 88	89 92 92 85 96 163	95 97 97 90 161 167 81	900 103 103 105 111 163 162 .3 .15	103 106 106	167 107	107 108 101 117 111 108 .3 15	210 00 00 601 601 101 101 100	112 113 113 103 115 120 119 112 ,3 .15	113 114 104 117 122 116 114 11	114 107 118 124 117	116 116 108 49 125 119 117 .3 115		•	OF	PC	POC	P-Q	AGI	15			
	INPUT FLOW GPM SFLOW	1		WATER	920	4-10	OFF	S- energy	440	DEF.	SOFE	DEF	DEF	OFF	DEF	SOFE			+						 	_	

DATE.

SIGNED

48 9254

ORDER NO.

SERIAL NO.

UNIT TEMPERATURE DATA

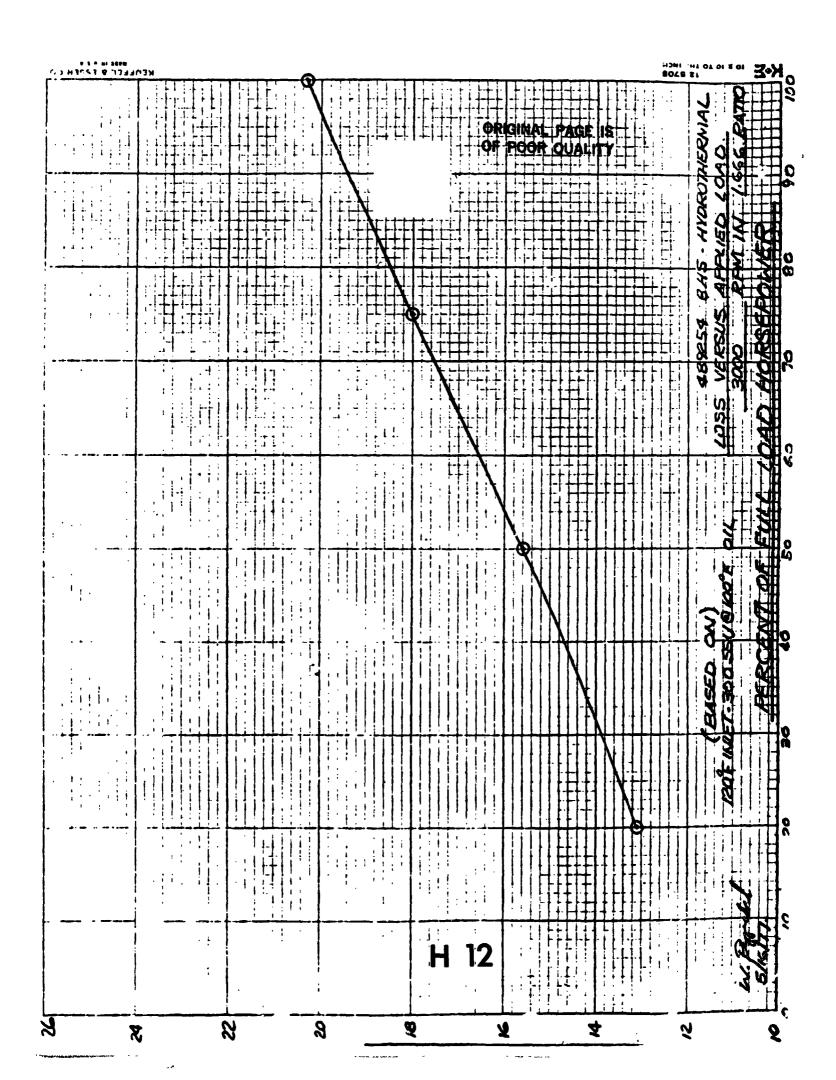
(Always accompany with P.G.C. Sheet No. ETL-1)

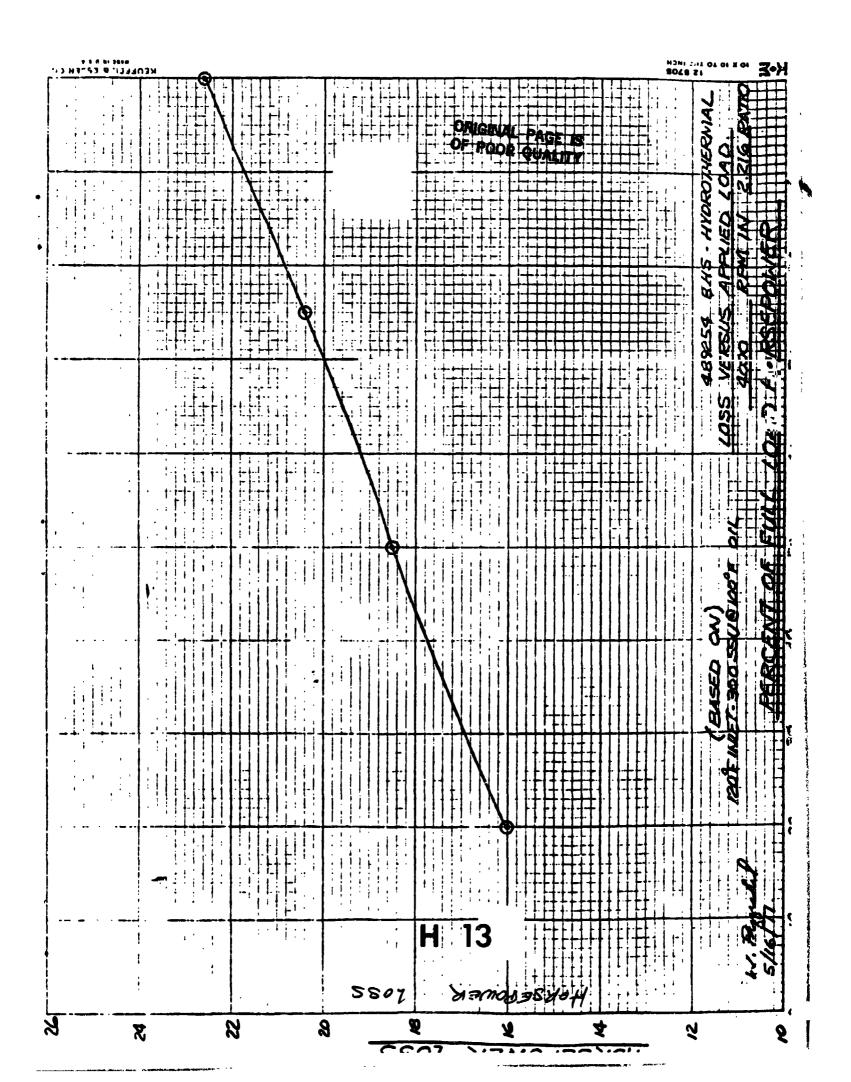
DATA MUST BE ACTUAL, NOT RATED VALUES; IF NOT MEASURED, LEAVE BLANK

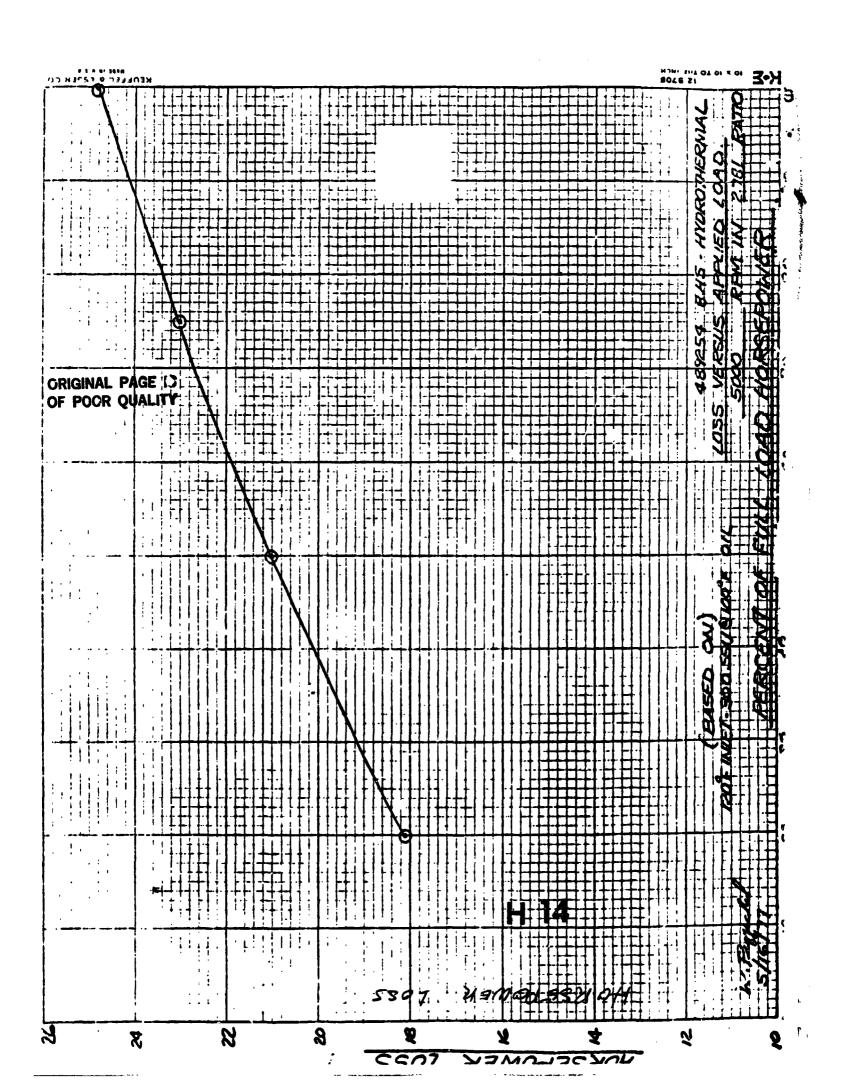
SERIAL NO -ON ,বয়ত

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esCombining Advanced Design with Proven Performance

RELATIONSHIPS OF SPEED, CAPACITY, PRESSURE, POWER CONSUMPTION

Table "A" below shows the capacity and suggested driving motor size for different speeds and pressures. These figures are based upon pumping a liquid of about 200 SSU viscosity with a 15 ' maximum vacuum. While Tuthill Series C pumps will develop as high as 27" of vacuum, it is sound engineering to reduce the vacuum to a minimum.

The speed of the pump must be reduced when handling liquids of high viscosity, and the size of lines increased to prevent cavitation, loss of capacity and high power requirements. For typical performance with liquids of varying viscosities kindly see chart "B" below. For speeds above 1800 rpm and fluid temperatures above 200° F, consult factory.

PUMP SPE	ED					18	00 RPI	M			•					1200	RPM		-		
OPERATI	NG	1	ð		50	1(DO	2	00	4	00	î	3	50		10	0	20	10	41	00
PRESSURE	PSI	GPM	HP	GPM	HP	GPM	HP	GFM	HP	GPM	HP	GPM	HP	GPM	HP	GPM	HP	GPM	HP	GPM	HP
	1	3.2	1/4	3.1	1/3	2.7	1/2					2.1	1/4	2	1/4	1.3	⅓3				
ш	2	9	1/2	8	3/4	7	11/2	61/2	2	5	3	61/2	1/3	6	1/2	51∕2	3/4	5	11/2	41/2	2
7 1 5	3	18	1	17	11/2	16	3	15	5	121/2	71/2	12	½	111/2	1	11	11/2	10	3	8	5
Ø	4	37	11/2	36	3	35	5	33	71/2	29	15	24	1	231/2	1.1/2	23	3	21	5	17	71/2
a	5	62	3	61	5	60	71/2	54	10	50	20	40	11/2	39	3	38	5	35	71/2	31	15
ā	6	84	5	83	742	82	10	80	15	78	25	56	3	5£	5	54	71/2	50	10	46	20
Q.	7				A							123	5	120	10	115	15	99	20		
	8				17							223	10	220	15	203	25	1.76	40		

HP. FOR MAIN LUBE OIL PUMP

BASED ON PUMPING LIQUIDS OF 200 SOU VISCOSITY

-	RPM		1	00			3	00	_		6	00			91	00			12	200			16	00	
PRE	SSURE	50-	P\$I	100-	PSI	50-1	SI	100-	PSI	50-	PSI	100-	PSI	50-	PSI	100-	PSI	50	-PSI	100	-PSI	50	-PSI	100	-PSI
PUMP	VISCOSITY SSU	GPM	нР	GPM	HP	GPM	HP	GPM	нР	GPM	нР	GPN.	НР	GPM	HP	GPM	HP	GPM	НР	GPM	НР	GPM	нР	GPM	НР
	500					1.3	1/8	1.2	1/4	2.4	1/4	2.0	₹3	4.0	33	3.3	1/2	5.3	¥ ₂	4.5	₹4	8.4	1	7.5	11/2
2C	1,000					1.6	1/4	1.5	¥ ⁄3	3.0	1/4	2.8	1/2	4.5	₹⁄2	3.8	3/4	6.0	3/4	5.8	1	9.2	1	9.0	11/2
1"	5,000		_			1.6	1/4	1.5	1/3	3.2	3/4	2.8	3/4	4.6	1	4.2	11/2	6.3	1/2	5.9	11/2	9.3	2	9.0	2
ports	10,000	.5	1/8	.5	¥6	1.6	1/3	1.5	1/2	3.2	3/4	2.8	3/4	4.9	1	4.7	11/2					L			
	25,000	.5	1/4	.5	1/4	1.6	1/2	1.5	₹4					Ĺ			:					<u> </u>			
	500					2.9	1/4	2.7	15	5.8	√2	5.7	3⁄4	8.9	1	8.5	11/2	11.9	11/2	11.5	2	17.5	2	16.5	3
3C	1,000					3.3	1/4	2.9	1/2	5.0	¾4	5.9	1	9.0	1	દૈ.ઉ	11/2	12.0	152	11.8	2	18.0	2	17.0	3
11/4"	5,000					3.0	1/2	2.9	¾	6.0	1	5.9	11/2	9.1	11/2	8.9	2	12.1	2	11.9	3	18.2	3	17.5	5
ports	10,000	1.6	1/4	.9	1/4	3.0	3/4	3.0	3/4	6.0	11/2	5.9	11/2	9.1	2	9.0	2								
	25,000	1.0	1/3	.9	₹2	3.0	¾	3.0	1		Lj											<u> </u>			
	500					5.8	1/3	5.5	1/2	11.8	1	11.5	11/2	17.8	11/2	17.5	2	22.8	2	.2.5	3	36.2	5	36.0	5
4C	1,000					5.9	1/3	5.7	3/4	11.9	1	11.7	11/2	18.0	2	17.8	3	23.0	3	22.8	5	36.5	5	36.3	5
11/2"	5,000					6.0	1/2	5.8	1	12.0	2	11.8	2	18.0	3	17.8	5	23.0	5	22.8	5	7.0	71/2	36.7	71/2
ports	10,000	1.9	15	1.3	1/3	6.1	3/4	6.0	11/2	12.0	2	11.8	3	18.0	3	17.8	5	23.0	5	22.8	5				
	25,000	1.9	1/3	1 9	'/ 2	6.1	1	€.0	11/2														<u>L_</u>		
	500					9.8	1/2	9	1	20.0	11/2	19.8	2	30.4	3	30.2	5	39	5	38.4	5	60.5	5	60	71/2
5C	1,000			i		10.0	₹2	9.5	1	20.2	11/2	20.0	3	30.6	3	30.4	5	39.5	5	39.0	5	61	71/2	60.5	71/2
11/2"	5,000					10.3	1	10.0	142	20.5	2	20.4	3	30.8	5	30.6	5	39.7	5	39.5	71/2	61.2	71/2	60.8	10
ports	10,000	3.1	V 3	3.0	1/2	10.3	1	10.0	11/2	20.5	2	20.4	3	30.8	5	30.6	3					L			
	25,060	3.1	₹2	3.0	3/4	10.3	11/2	10.0	2																
	500					13.5	3/4	13.0	1	27.0	2	26.5	3	40.5	5	40.0	5	54.5	5	54.0	742	83.0	742	82.0	10
6C	1,000					13.6	3/4	13.2	11/2	27.4	2	27.0	3	40.8	5	40.3	5	55.0	5	54.5	742	83.7	71/2	83.2	10
2"	5,000					13.8	1	13.5	11/2	27.8	3	27.5	3	41.0	5	40.5	742	55.2	742	54.7	10	54.0	10	80.5	15
ports	10,000	4.6	1/3	4.5	½	13.8	2	13.5	2	27.8	5	27.5	5	41.0	742	40.5	71/2	55.2		54.7	10				
	25,000	4.6	1/2	4.5	3∕4	13.8	2	13.5	3																

H15

TEST REPORT

ALTERNATOR

Manufacturer	Kato Engineering Co
Buyer's P.O.4	THE 12- PRIME
Specification #	
Buyer's Serial #	
Manufacturer's Ser. #	SIN 74526

ADMINISTRATIVE DATA

Testing Organization	KATO ENGINEERING CO.
Test Performed By	(1) C. LEIFERMAN
	(2) J. MORT Z
	(3)
	(4)
Test Performed On	
performed in accordance with tes	t of my knewledge all tests were t specifications in senting these tests is contained

Signature and Title

KATO ENGINEERING COMPANY Mankato, Minn.

ORIGINAL PAGE IS OF POOR QUALITY

LIST OF SYMBOLS

ACV	Generator output voltage
ACI	Generator output current
KVA	Kilovolt-amperes
KW	Power output or input in kilowatts
PF	Power Factor
GFV	DC voltage generator field
GPI	Generator field amps
V _{rp}	Rated phase voltage
	Rated phase current
Irp	Ammeter reading
I-L	Line to Line
L-N	Line to Neutral
RPM	Revolutions per minute
~~	Ohms
Lbs.	Pounds
Ft.	Feet
Dyn	Dynamometer
CT	Current Transformer
	Direct axis synchronous reactance
₩1.	Direct asix transient reactance
X'd X'd X'd	Direct axis subtransient reactance
sck	Short Circuit Ratio
X ₂	Negative sequence reactance
X _o	Zero sequence reactance
MFI	Motor Field Current
MFV	Motor Field Volts
Motor EFI	Motor exciter field current
Motor EFV	Motor Exciter field volts
Pal	Frequency no load
-ni Per	Frequency full load
F _{f1}	Voltage no load
v ^{nl} vfl	Voltage @ full load
If1	Line current @ full load
1-2,2-3,3-1	Three phase terminal to terminal readings
1-2-3	Three phase line currents
Vave	Average of the three phase voltages
Iave	Average of the three line currents
CC res	Cross current resistor
CC Comp	Cross current compensation
ZFI (Gen.)	Exciter field amps
EFV (Gen.)	Exciter field volts
NA	Not applicable
CWFDE	Clockwise facing drive end
CCWFDE	Counterclockwise facing Jrive end
EFF	Efficiency
T'do	Direct axis transient open circuit time constant
T'd	Direct axis transiert short circuit time constant
W&F	Windage & Friction
CL	Core loss
SLL	
	Stray load loss

KATO ENGINEERING COMPANY

SYNCHRONOUS MACHINE COMMERCIAL TEST

KM	К	VA	P.F.	RPM	PH/	ASE	FREQ.	٧	OLTS	A	MPS	SERIA	AL NO.	UNIT
100	0 12	50	3.0	<u> 2</u>	3	*	60	4	30	13	04	745	526	1
CUSTOMER		Swei	HAR	t e	LE			Co	コへ	ر م	ATE:		23/7	6
RESISTAN				TED BY								منجو		
ARM 1-2	0.002	93	~@ <i>Z3</i> . (9°c.	GEN F	LO	1.36	66	~@Z	3. & c.	CODE	4	P6-2	2175
		93			EXC F		11.9	9	∧eZ	3.8°C.	TYPE	ع	385	6
		293							. V6	oC.	MODE	L 10	DOER	95
SATURATI	ON CURVE													
ACV	ACI	KVA	KW	P.	F.			OCV	EFI	HZ	EXCIT	TATION	SEP	
696	0							58.7	5.00	60	EXC.	POLARITY	F	7
679	0							7.3	4.00	60	RES.	VOLT.	39.0	
646	0							<u>557</u>	3.00		CONN	ECTED A	Y	
588	0								2.00		ROTA	TION	ew F	
528	0							6.8	1.43	60	SEQU	ENCE	7, -7	
480	٥							133	1.16	60	COMM	RUNOUT	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	
456	0				\Box			122	1.07		COM	UTATION.	Baush	لون
384	0					_		89	.77	-10	RADI	O SUPPRES	NOIS	
240	0							49	.442	(0)	BEAR	INGS	0X	
							•	· ·			·	MECH.	BAL: (P - P)	
			<u> </u>			DR. E	NO = 6							
180	1509	1250	-	0	3.17	63	OPP. E	ND = 0 -	•••••					
650	0			_	3.17	6-								
			<u> </u>				(MINIMUM)							
					EXCI	TER 🗅	-07							
		L		┵.							P.M. F	LO.		
								-	<u> </u>				IC STRENGT	TH
41 2011	4050 OF 1	EADO									GEN	ARM -		VOLT
	MBER OF LI	OR <u></u>	LEADS	WHEN S	HIPPE	D.					GEN	FLD		VOLT
3) VOI	TAGE REG	ULATOR M	IONEL		-	_	S/N _		· · · · · · · · · · · · · · · · · · ·		EXC	ARM		VOLT
4) VO	LTAGE ADJ	UST RANG	E:		***.	_ TO		<u> </u>	١ ـــــــ	/AC	EXC	FLD		VOLT
									1		PM	FLD	<u> </u>	VOLT
<u></u>												NSULATION	RESISTAN	ICE
HEMARKS	, ,	•			GENERA	ATOR	GEN	ARM		MEG-				
i				AMP	GEN	FLO		MEG-						
1				-	EXC	ARM		MEG						
		001	GINA	GE	IS			Į.	4 -		EXC	FLD		MEG~
		OF		PM	FLD		MEG ~							
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KATO ENGINEERING COMPANY

SYNCHRONOUS MACHINE COMMERCIAL TEST

KW		(VA	P.F.	RPM	PHASE	FREQ.	VC	DLTS	AMP	s	SERIA	AL NO)	UNIT]
1000	0 16	50	7.8	1800	30	60	277	1480	150	6	745	26		1]
CUSTOME	R: 54	ein	HA	RI	ELE	c. (20		DAT	E: //	1-30	-76	2		_
RESISTAN	CE:		TE	STED BY	J. M	ROT	<u> </u>	Ku	TOE	CK	-C.1	EL	LE.	RMA	2/
		193	^@25	80c.	GEN FLD	1.34	4	~@_13	goc.	CODE	14	26	- 4	175	7
					EXC FLD					TYPE					ł
	0.00						<u></u>	∿6		MODEL				7 =	1
SATURATI		<i></i>				,						<u> </u>			3
ACV	ACI	KVA	KW	P.1	F.	1	DCV	EFI	HZ	EXCITA	ATION	RF	4		1
						•				EXC. PO	DLARITY	Fo	2 = 7		1
										RES. V	OLT.				1
										CONNE	CTED A		_ Y.	1]
										ROTAT	ION (2 Lu	Fí ر)E	1
										SEQUE	NCE]
								ľ		COMM	RUNOUT	BRL	ISH	Les	1
											JTATION]
										RADIO	SUPPRES	SION		-]
						İ				BEARI	VGS]
						•] [MECH.	BAL:	(P - P)		
										DR. EN	0=0.				
										OPP. EN	D = 0 +		-]
			<u></u>												
									<u>.</u> .		AIR GAP	(MINI	MUM)		_
										EXCITE	R Ju	eR:	0.0	24']
] [P.M. FL]
											HELECTR	IC ST	RENGT	H	_
4) 100	ABER OF L	CADC	,,					_		GEN A	RM -	ور	-0	VOLT]
	INECTED F			WHEN S	HIPPED.					GE: F	נס /	5	0 9	VOLT	
	TAGE REG					S/N			_	EXC A	PM .	15	0 0	VOLT	
4) VOL	TAGE ADJ	UST RANG	E:		TO			VA	c [EXC F	LO	15	00	VGLT	Ĺ
									l	PM F	LO .			VOLT	
				·						IN	SULATION	RES	ISTAN	CE	•
REMARKS	5							GENERAT	DR	GEN A	RM OU	د تد_	100	MEG~	
							VO	LT A	MP.	GEN F	به ۱۵	E R	140	MEG-^	1
				10		•	•			EXC A	RM O	u &	2100	MEG∧	1
		ORIGI	NAL P	AGE IS) /		I-5	工		EXC FI	LD OU	ER	100	MEG.^	1
		OF P	UUK Ų	UALITY	•		гЭ			PM F	LO	~		WEG~	J
						1		,							7
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							T ₂ :	48	2.1	1 2	77	2	15	06	-

	OR OF	IGIN/	AL PAI	GE 18 ALIT	}		F	A V 5.	_			[]		17	1.31			M	1 12		FT
-30-76			T. MROT Z	LEIFERMAN		والمسترب بالمراجعة مدير والمناب والمناب والمراجعة والمناب	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1		1 WHI, KOSS/L.	1,7°C 11ts (185 /2)	1142 40 157 1358 73.6	129 40 2225 2337 85.6	1.67 4.881 097 01, 6271	14:7 40 276.5 236.4 855	115 5 40 1617 139.8	0-7 Lh 30.	2	9 /60		2 2 2 2 2 3 3 3 3 3 3 3 3 3 3 3 3 3 3 3	= 3.15 LBS @ 3.5
DATE	SPEC.	METHOD	LECTUL TESTED BY _		GOV'T. INSP.		9	67 1	Tingel C	RPM fro-	100, 100 1725 113.4	100 200 1745 113.K	124, 227, 121, 191	100 202 1741 1145	100 aa.1 1223 114.9	4.2 / 20, //0 /		C8Z/	उत्त प्रमा	(16 0 (13 (-3:	DRIVE LOSS
T RECORD	ENGINEERING CO.	MANKATO, MINNESOTA U.S.A.		ACI NO.	FEICIFNCY		15.21		/w. /wz 16	SULVEM) SULTY	496 504 10	998 1002 10	316 234 11	587 1442	1633 - 803 16	200		422 78	3220 70	5252	WHERE
TEST	KATO ENG	MANKATO, A	CUSTOMER SINHAR	- 1	TEST LEEL		REPEAT	-		V EFVEF	221 441 7	5 158134		2 18.0 1.55	2 37.2 3.18	077 701	5%/	1561	92.42	100/ 573/0	135.8 - 13.6%
-26-1	,	KW /COD	RPM 1200	WFOE						HZ PF GET GFV	521 1.0 26.7 826	581 1.0 27.8 39.5	0111 8.35 3.5 185	0.5 4/ 232.	2.59 5.49 16.2	782 0 0 648 35.0	-38:7	328 0.66 505 348	A D TV:	Pout	NI
 SERIAL NO. 745	10.	450	FREG. 60	NOL NOL	באכוואוטא			H		75,77,37	34 . 70.0 (20	040 048	4800 50	C. 25.6 30050	1.21 11500 1506	1.4 Web 271	Z C.9%	3 the 480.0 876	100 LO	E C C IVIENI	
<i>~</i>	, , (I	•	:NST.	READ.	C7. 73	FACTOR		73.7	100		-	22.5		3/2		Ad Marion	ا.

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100 % LOAD

EFFICIENCY CALCULATIONS

KATO ENGINEERING CO.

Mankato, Minnesota

S/N 74526 MODEL 1000 ER9E METHOD 115 DATE /1-30-77

A. Friction & Windage Loss (No Excitation)

Watts =
$$\frac{F L N}{5252}$$
 x 746

Where: F = NET FORCE IN LBS.

L = LEVER ARM IN FT.

N = SPEED OF DYNOMOMETER IN RPM

B. Core Loss + Windage and Friction (@ Rated Voltage)

Watts =
$$\frac{F L N}{5252}$$
 x 746

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Core Loss B-A

C. Armature Copper Loss (Stray Load Loss Test)

Where: I = RATED ARMATURE CURRENT

$$= (1504)^2 (.00155) (3)$$

R = ARMATURE RESISTANCE PER PHASE AT TIME OF THE STRAY LOAD LOSS TEST.

= 105/8 KITS

D. Stray Load Loss + I²R Loss + Friction & Windage (@ Rated Armature Current)

Watts =
$$\frac{F L N}{5252} \times 746$$

= $\frac{(46.05)(6.6)(1793)}{5252} \times 746$

- 41048 WATTS

Stray Load Loss = D-(A + C)

100 % LOAD EFFICIENCY CALCULATIONS

KATO ENGINEERING CO.

Mankato, Minnesota

S/N 74526 MODEL 1000 ER9E MIL-STD-705 METHOD 415.0 DATE

E. Armature I²R Loss

Watts =
$$I^2_{arm} \times R_{75} \times 3$$

F. Generator Field I² X R Loss

Where: if = FIELD CURRENT AT RATED LOAD

$$\frac{R_{75}}{234.5 + 23.8} \times 1.366$$
 ohms

Total Losses (Watts)

110

75 % LOAD

EFFICIENCY CALCULATIONS

KATO ENGINEERING CO.

Mankato, Minnesota

S/N 74526 MODEL 1000 ER9E MIL-STD 705 METHOD 115.0 DATE 11-30-77

A. Friction & Windage Loss (No Excitation)

Watts =
$$\frac{F L N}{5252}$$
 x 746

Where: F = NET FORCE IN LBS.

L = LEVER ARM IN FT.

N = SPEED OF DYNOMOMETER IN RPM

4

- 27083 WATTS

B. Core Loss + Windage and Friction (@ Rated Voltage)

Watts = $\frac{F L N}{5252}$ x 746

Core Loss B-A

* <u>.___</u> - ___ = 8502 WATTS

C. Armature Copper Loss (Stray Load Loss Test)

Watts = $I_{arm}^2 \times R \times 3$

Where: I = RATED ARMATURE CURRENT

 $= ()^2 () (3)$

_____ WATTS

R = ARMATURE RESISTANCE PER PHASE

AT TIME OF THE STRAY LOAD

LOSS TEST.

D. Stray Load Loss + I²R Loss + Friction & Windage (@ Rated Armature Current)

Watts = $\frac{F L N}{5252}$ x 746

= ____ 1 746

1-11 - WATTS

Stray Load Loss = D-(A + C)

75 % LOAD EFFICIENCY CALCULATIONS

KATO ENGINEERING CO.

MODEL MIL-STD-705 **METHOD 415.0**

S/N

Mankato, Minnesota

E. Armature I²R Loss

Watts =
$$I^2 arm \times R_{75} \times 3$$

= ()² () (3)

$$(11,912)$$
 $\frac{3}{4}$ = 6700 Watts

$$R_{75} = \frac{234.5 + 75}{234.5.2} X$$
 ohms

F. Generator Field I² X R Loss

$$I_{FLD} = \frac{3}{4}L_{A10} = (I_{FLD} + I_{NL})\frac{3}{4} + I_{NL}$$

$$= (60 - 27.2)\frac{3}{4} + 77.2$$

$$= \frac{234.5 + 75}{234.5 + } \cdot x \quad \text{ohm}$$

ohms

$$WAFTS = I^{2}R$$

$$= (51.8)^{2} (1636)$$

$$= 4390$$

$$= \frac{234.5 + 75}{234.5 +} \cdot X \qquad \text{ohms}$$

Total Losses (Watts)

ohms

1. Friction & Windage Loss	27083
2. Core Loss	8502
3. Stray Load Loss	1939
4. Armature I ² R Loss —————	6700
5. Field I2R Loss	4390
6. EXCITER -	595
Efficiency:	49209

50 % LOAD EFFICIENCY CALCULATIONS

KATO ENGINEERING CO.

Mankato, Minnesota

S/N 74526 MODEL 1000 ER9E MIL-STD 70S METHOD 1/5:0 DATE 1/-23.76

A. Friction & Windage Loss (No Excitation)

Watts =
$$\frac{F L N}{5252}$$
 x 746

Where: F = NET FORCE IN LBS.

L = LEVER ARM IN FT.

. 5252 x 746

N = SPEED OF DYNOMOMETER IN RPM

- 27083 WATTS

B. Core Loss + Windage and Friction (@ Rated Voltage)

Watts =
$$\frac{F L N}{5252}$$
 x 746

* ---- x 746

watts

Core Loss B-A

= 8502 WATTS

Armature Copper Loss (Stray Load Loss Test)

Watts = $I_{arm}^2 \times R \times 3$

Where: I = RATED ARMATURE CURRENT

* ()² () (3)

R = ARMATURE RESISTANCE PER PHASE AT TIME OF THE STRAY LOAD

...

• WATTS LOSS TEST.

D. Stray Load Loss + I^2R Loss + Friction & Windage (@ Rated Arm .ure Current)

Watts =
$$\frac{F L N}{5252}$$
 x 746

Stray Load Loss = D-(A + C)

$$(3447)(\frac{1}{2})^2 = 862 - \longleftrightarrow$$

50 % LOAD EFFICIENCY CALCULATIONS

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KATO ENGINEERING CO.

Mankato, Minnesota

S/N 745.26 MODEL 1000 ER9E MIL-STD-705 METHOD 415.0 DATE 11-30-76

E. Armature I²R Loss

Watts =
$$I^2_{arm} \times R_{75} \times 3$$

= $()^2 () (3)$
 $(\frac{1}{2})(1/,9/2) = 2978$ Walts

Where: I = RATED ARMATURE CURRENT

R75 = RESISTANCE PER PHACE Corrected to 75°c

$$R_{75} = \frac{234.5 + 75}{234.5.2} \times \text{ohms}$$

$$= \frac{309.5}{234.5.2} \times \text{ohms}$$

ohms

F. Generator Field I² X R Loss

= 3110

$$I_{FLO} = 50\% = (I_{FL} - I_{NL}) \frac{1}{2} + I_{NL}$$

$$= (60 - 37.2) \frac{1}{2} + 27.2$$

$$= 43.6$$

$$WATTJ = I^{2} R$$

$$= (43.6)^{2} (1.626)$$

Where: If = FIELD CURRENT AT RATED LOAD

R75 = RESISTANCE OF THE FIELD CORRECTED TO 75°c

 $R_{75} = \frac{234.5 + 75}{234.5 +} \cdot X$ ohms

= 309.5 X ohms

ohms

Cotal Losses (Watts)

= 100 - 7.912

1 Eff. = 92.08

114

"

20 % LOAD EFFICIENCY CALCULATIONS

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Mankatu, Minnesota

S/N 74625 MODEL 1000 ER92 MIL-STD 705 METHOD 1.5-0 DAT 11-30-76

A. Friction & Windage Loss (No Excitation)

Watts =
$$\frac{F L N}{5252}$$
 x 746

Where: F = NET FORCE IN LBS.

L . LEVER ARM IN FT.

5252 x 746

N = SPEED OF DYNOMOMETER IN RPM

- 27083 WATTS

B. Core Loss + Windage and Friction (@ Rated Voltage)

Watts = $\frac{F L N}{5252}$ x 746

* ____ x 74

• WATTS

Core Loss B-A

= 8502 WATTS

C. Armature Copper Loss (Stray Load Loss Test)

Watts = $I_{arm}^2 \times R \times 3$

Where: I = RATED ARMATURE CURRENT

* ()² (') (3)

• _____ WA.FTS

R = ARMATURE RESISTANCE PER PHASE AT TIME OF THE STRAY LOAD

LOSS TEST.

D. Stray Load Loss + I²R Loss + Friction & Windage (@ Rated Armature Current)

Watts = $\frac{F L N}{5252} \times 746$

5252 x 746

• ______ MATTS

1-15

Stray Load Loss = D-(A + C)

20% LOAD EFFICIENCY CALCULATIONS

KATO ENGINEERING CO.

Mankato, Minnesota

S/N 74625 MODEL 1000 ER9E MIL-STD-705 METHOD 415.0 DATE 1/- 30-76

E. Armature I²R Loss

Watts =
$$I^2 arm \times R_{75} \times 3$$

= ()² () (3)

$$R_{75} = \frac{234.5 + 75}{234.5 + 3} \times \text{ohms}$$

$$= \frac{309.5}{234.5 + 3} \times \text{ohms}$$

$$I_{FLO} = (I_{FL} - I_{NL})(\cdot 2) + I_{NL}$$
$$= (60 - 27.2)(\cdot 2) + 17.2$$
$$= 33.76$$

WATTS =
$$I^2R$$

=(33.76)²(1636)
= WATTS

ohms

Total Losses (Watts)

10 % LOAD EFFICIENCY CALCULATIONS

KATO ENGINEERING CO.

Mankato, Minnesota

S/N 74526 MODEL 1000 ESPE MIL-STD 705 METHOD 1/5:0 DATE 11-30-76

		_		_		` _	
A.	Friction	6	Wirdage	Loss	(No	Excitation (m)

Watts = $\frac{F L N}{5252} \times 746$	Where: F = NET FORCE IN LBS.
	L = LEVER ARM IN FT.
. 5252 x 746	N = SPEED OF DYNOMOMETER
- 27083 WATTS	

B. Core Loss + Windage and Friction (@ Rated Voltage)

Watts =
$$\frac{F L N}{5252} \times 746$$

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IN RPM

Core Loss B-A

= 8502 WATTS

C. Armature Copper Loss (Stray Load Loss Test)

D. Stray Load Loss + I²R Loss + Friction & Windage (@ Rated Armature Current)

Watts =
$$\frac{F}{5252} \times 746$$

= $\frac{}{5252} \times 746$
= $\frac{}{5252} \times 746$
Stray Load Loss = U -(A + C)

EFFICIENCY CALCULATIONS

S/N 74526 MODEL 1000 ER9E MIL-STD-705

KATO ENGINEERING CO.

METHOD 415.0

Mankato, Minnesota

DATE 30 NOV 1976

E. Armature I²R Loss

Where: I = RATED ARMATURE CURRENT

Watts = I^2 arm $X R_{75} X 3$) (3) (-1)(11,912) = 119

R₇₅ = RESISTANCE PER PHASE Corrected to 75°c

= 309.5 x

ohms

ohms

F. Generator Field I² X R Loss

Where: If - FIELD CURRENT AT RATED LOAD

I FLD = (IFL -INL)(1) +INL =(60-27.2)(.1)+27.2

RESISTANCE OF THE FIELD CORRECTED TO 75°c

= 30.48

WATTS = IZR = (30.48) 2 (1.636) = 1520 WATTS

Total Losses (Watts)

ohms

1. Friction & Windage Loss	27083
2. Core Loss	8502
3. Stray Load Loss —————	35
4. Armature I ² R Loss	119
5. Field I ² R Loss	1520
6. ExCITER -	188
Efficiency: —	
· *	27/11/2

\$ Eff. = 100 - Losses x 100 Output + Losses

= 100 - <u>(37442) (100)</u> /00,000 * 37442

= 100 - 27.24

\$ Eff. - 72.75

I-18

ORIGINAL PAGE IS OF POOR QUALITY	EFFICIENCY CALC KATO ENGINEERI Mankato, Minn	NG CO.	S/N 74526 MODEL 1008 E MIL-STD 705 METHOD 115-0 DATE 30 Nov	er9E
A. Friction & Windage	Loss (No Excitati	on)		
Watts = $\frac{F L N}{5252} \times \frac{1}{5252}$	746	Where: F	= NET FORCE IN LES.	•
•		L	- LEVER ARM IN FT.	,
. 5252	x 746	N :	SPEED OF DYNOMOME	TER IN RPM
= <u>27083</u>	3 WATTS		•	
B. Core Loss + Windage	and Friction (e R	ated Voltage)		
Watts = $\frac{F L N}{5252} \times 74$	46	•		
•	x 746			
= ·	WATTS .		•	. •
Core Loss B-A	·		.•	<u>.</u> -
*	•		•	
= 8502	WATTS		•	
C. Armature Copper Loss		Test)		
Watts = I ² arm x R x		Where: I =	RATED ARMATURE CUI	RENT
• () ² (() (3) Watts	R =	ARMATURE RESISTANCE AT TIME OF THE STELLOSS TEST.	
D. Stray Load Loss + I ²		& Windage (0		rent)
Watts = <u>F L N</u> x 74			*	
5252	x 746		• .	
5252	WATTS		-	•
Stray Load Loss = D-		119		
	1202 - (+			

WHERE 1202 = I ... @ 1000 KW 1.0 PE

100 % LOAD (1.0 PF)

EFFICIENCY CALCULATIONS

KATO ENGINEERING CO.

Mankato, Minnesota

S/N 74526 MODEL 1000 ER9E MIL-STD-705 **METHOD 415.0** DATE 30 NOU 1976

E. Armature I²R Loss

Watts =
$$I^2_{arm} \times R_{75} \times 3$$

= $()^2 () (3)$

Wilete: I RATED ARMATURE CURRENT

R75 = RESISTANCE PER PHASE Corrected to 75°c

 $\frac{R75}{234.5} = \frac{234.5 + 75}{234.5}$ ohms ohms

F. Generator Field I² X R Loss

$$warrs = I^2 R$$

= $(37.3)^2 (1.636)$
= 3276

Where: If = FIELD CURRENT AT RATED LOAD

> = RESISTANCE OF THE FIELD CORRECTED TO 75°c

ohms

ohms*

Total Losses (Watts)

- 100 - 4.58

4 Eff. - 95.4

1-20

75 % LOAD 1.0 PF

- EFFICIENCY CALCULATIONS

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KATO ENGINEERING CO.

Mankato, Minnesota

S/N 745 2 6
MODEL 1000 ER1E
MIL-STD 705
METHOD 415.0
DATE 30 NOU 1976

A. Friction & Windage Loss (No Excitation)

Watts • $\frac{F L N}{5252}$ x 746

Where: F = NET FORCE IN LBS.

L = LEVER ARM IN FT.

5252 x 746

N = SPEED OF DYNOMOMETER IN RPM

= 27083 WATTS

B. Core Loss + Windage and Friction (@ Rated Voltage)

Watts = $\frac{F L N}{5252}$ x 746

* x 746

- WATTS

Core Loss B-A

* 8502 WATTS

C. Armature Copper Loss (Stray Load Loss Test)

Watts = $I_{arm}^2 \times R \times 3$

Where: I = RATED ARMATURE CURRENT

 $= ()^2 () (3)$

R = ARMATURE RESISTANCE PER PHASE

AT TIME OF THE STRAY LOAD

LOSS TEST.

D. Stray Load Loss + I2R Loss + Friction & Windage (@ Rated Armature Current)

Watts = $\frac{F L N}{5252}$ x 746

* ____ x 746

* WATTS

Stray Load Loss - D-(A + C)

1-21

(889) 2 (3447) · 1205 - (· · ·

75 % LOAD @ 1.0 PF

EFFICIENCY CALCULATIONS

KATO ENGINEERING CO.

Mankato, Minnesota

S/N MODEL MIL-STD-705 METHOD 415.0

DATE

E. Armature I²R Loss'

Watts =
$$I^2_{arm} \times R_{75} \times 3$$

= ()² () (3)
(11912) $\left(\frac{889}{1504}\right)^2 = 4162$ Watts

Where: I = RATED ARMATURE CURRENT

R75 = RESISTANCE PER PHASE Corrected to 75°c

$$R_{75} = \frac{234.5 + 75}{234.5 + 2} X$$
 ohms $= \frac{309.5}{2} X$ ohms

ohms

F. Generator Field I² X R Loss

$$warrs = T^2R$$

=(34.4) (.636)
= 1936

Where: If . FIELD CURRENT AT RATED LOAD

R75 = RESISTANCE OF THE FIELD CORRECTED TO 7.5°c

 $R_{75} = \frac{234.5 + 75}{234.5 +} \cdot X$ ohms

= 309.5 X ohms

ohms

Total Losses (Watts)

\$ Eff. - 94.55

122

50 % LOAD CI.OFF EFFICIENCY 'ALCULATIONS

KATO ENGINEERING CO.

Mankato, Minnesota

S/N 74526 MODEL 1000 ER9E MIL-STD 705 METHOD 1150 DATE 30 NOV 1976

A. Friction & Windage Loss (No Excitation)

Watts =
$$\frac{F L N}{5252} \times 746$$
 Where: F = NET FORCE IN LBS.

L = LEVER ARM IN FT.

N = SPEED OF DYNOMOMETER IN RPM

= $\frac{27083}{1}$ WATTS

B. Core Loss + Windage and Friction (@ Rated Voltage)

Core Loss B-A

C. Armature Copper Loss (Stray Load Loss Test)

Watts =
$$I^2_{arm} \times R \times 3$$
 Where: I = RATED ARMATURE CURRENT
= ()² () (3) $R = ARMATURE RESISTANCE PER PHASE AT TIME OF THE STRAY LOAD LOSS TEST.$

D. Stray Load Loss + I²R Loss + Friction & Windage (@ Rated Armature Current)

50 % LOAD e 1.0PF EFFICIENCY CALCULATIONS

KATO ENGINEERING CO.

Mankato, Minnesota

S/N 74526 MODEL /000 ER96 MIL-STD-705 METHOD 415.0 DATE 30 NOV 1976

E. Armature I²R Loss'

Watts =
$$I^2_{arm} \times R_{75} \times 3$$

= ()² () (3)

F. Generator Field I² X R Loss

$$I_{FLO} = (37.3 - 26)(5) + 26$$
$$= 31.65$$

$$WATT6 = I^2 R$$

= $(31.65)^2 1.636$
= 1639

Where: I = RATED ARMATURE CURRENT

R75 = RESISTANCE PER PHASE Corrected to 75°c

$$R_{75} = \frac{234.5 + 75}{234.5 + 2} \times \text{ohms}$$

$$= \frac{309.5}{2} \times \text{ohms}$$

ohms

Where: If = FIELD CURRENT AT RATED LOAD

R75 = RESISTANCE OF THE FIELD CORRECTED TO 75°c

 $\frac{R}{75} = \frac{234.5 + 75}{234.5 + } \cdot X$ ohms

= 309.5 X ohms

ohms

· Total Losses (Watts)

= 100 - 7.39

\$ Eff. - 92.61

1-24

20% LOAD @ 1.0PF

EFFICIENCY CALCULATIONS

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KATO ENGINEERING CO.

Mankato, Minnesota

S/N 74526 MODEL 1000 ER9E MIL-STD 705 METHOD 415.0 DATE 30 NOU 1976

A. Friction & Windage Loss (No Excitation)

Watts =
$$\frac{F L N}{5252}$$
 x 746

Where: F • NET FORCE IN LBS.

L = LEYER ARM IN FT.

5252 x 746

N = SPEED OF DYNOMOMETER IN RPM

C)

- 27083 WATTS

B. Core Loss + Windage and Friction (@ Rated Voltage)

Watts = $\frac{F L N}{5252}$ x 746

* ____ x 74

- WATTS

Core Loss B-A

= 8502 WATTS

C. Armature Copper Loss (Stray Load Loss Test)

Watts = $I_{arm}^2 \times R \times 3$

Where: I = RATED ARMATURE CURRENT

 $()^2 () (3)$

watts

R = ARMATURE RESISTANCE PER PHASE AT TIME OF THE STAY LOAD

LOSS TEST.

D. Stray Load Loss + I²R Loss + Friction & Windage (@ Rated Armature Current)

Watts = $\frac{F L N}{5252}$ x 746

= x 746

• _____ WATTS

1-25

Stray Load Loss = D-(A + C)

EFFICIENCY CALCULATIONS

S/N MODEL

KATO ENGINEERING CO.

MIL-STD-705 **METHOD 415.0**

Mankato, Minnesota

E. Armature I²R Loss'

Watts =
$$I^2$$
arm X R₇₅ X 3
 $\left(\frac{240}{1504}\right)(11912) = (11912)$

Where: I - RATED ARMATURE CURRENT

R75 = RESISTANCE PER PHASE Corrected to 75°c

$$R_{75} = \frac{234.5 + 75}{234.5 + 2} \times \text{ohms}$$

$$= \frac{309.5}{2} \times \text{ohms}$$

ohms

F. Generator Field I² X R Loss

$$I_{FLU} = (37.3 - 26)(.2) + 26$$

= 28.26
WATTS = $I^{2}R$

$$WATTS = I^{2}R$$

$$= (28.26)^{2} (1.636)$$

$$= 1306$$

Where: I} * FIELD CURRENT AT RATED LOAD

> . RESISTANCE OF THE FIELD CORRECTED TO 75°c

ohms

ohms

Total Losses (Watts)

Efficiency:

I-26

		·
A. Friction & Windage Loss (No Excitation	on)	
$Watts = \frac{F L N}{5252} \times 746$	Where:	F - NET FORCE IN LBS.
	·	L = LEVER ARM IN FT.
- 5252 x 746	•	N = SPEED OF DYNOMOMETER IN RPM
	•	
= 27083 · WATTS		
B. Core Loss + Windage and Friction (0 Ra	sted Volta	age)
Watts = $\frac{F L N}{5252} \times 746$	•	
* x 746	•	
- WATTS		•
Core Loss B-A		
•		
= 8502 WATTS		
C. Armature Copper Loss (Stray Load Loss	Test	
_		
Watts = I ² x R x 3	Where.	I - RATED ARMATURE CURRENT
= (). ² () (3) = WATTS		R = ARMATURE RESISTANCE PER PHAST. AT TIME OF THE STRAY LOAD LOSS TEST.
D. Stray Load Loss + I ² R Loss + Friction	& Windago	
	4 writeage	(a nated Asiacture Current)
$\frac{\text{Matts}}{5252} = \frac{\text{F L N}}{5252} \times 746$		
\$252 x 746		
NATTS		
Stray Load Loss = D-(A + C)	1-27	
1 120 3447 = 22 - (- +		•
(1504)		

10 % LOAD C 1.0 PF EFFICIENCY CALCULATIONS

KATO ENGINEERING CO.

Mankato, Minnesota

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OF POOR QUALITY

5/N 74526

MIL-STD 705 METHOD 415.0

MODEL 100 0 E 296

DATE 30 NOV 1976

10 % LOAD @ 1.0 PF EFFICIENCY CALCULATIONS

KATO ENGINEETING CO.

Mankato, Minnesoca

S/N 74526 MODEL :000 ER9E . MIL-STD-705 METHOD 415.0 DATE SO NOV 1977

E. Armature I²R Loss'

Watts =
$$I^2_{arm} \times R_{75} \times 3$$

= $()^2 () (3)$
= $(1/9/2) = 76.0$ Watts

Where: I = RATED ARMATURE CURRENT

R75 = RESISTANCE PER PHASE Corrected to 75°c

$$R_{75} = \frac{234.5 + 75}{234.5 + 20} \times Ohms$$

$$= \frac{309.5}{234.5 + 20} \times Ohms$$

ohas

$$I_{FLU} = (37.3 - 26)(.1) + 26$$

= 27.13

Where: if = FIELD CURRENT AT RATED LOAD

R75 = RESISTANCE OF THE FIELD CORRECTED TO 75°c

 $\frac{R_{75}}{234.5 + 75} = \frac{234.5 + 75}{234.5 +} \cdot X$ ohms

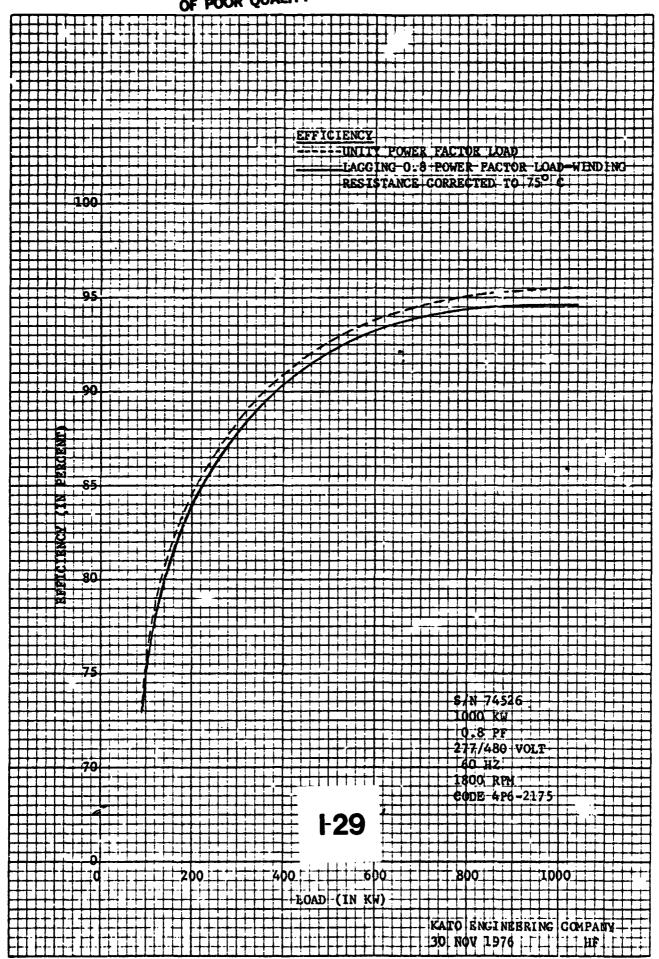
309.5 X ohms

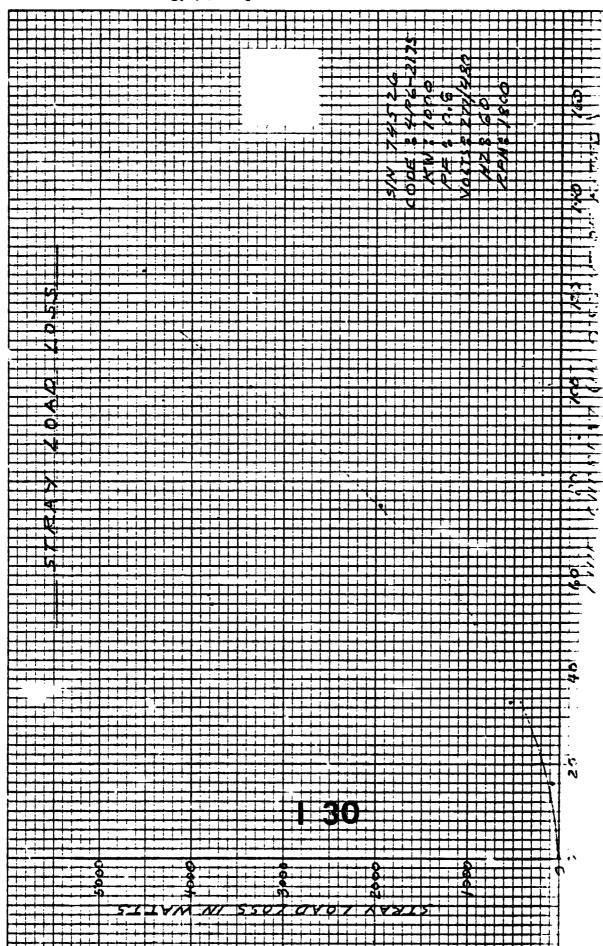
ohms

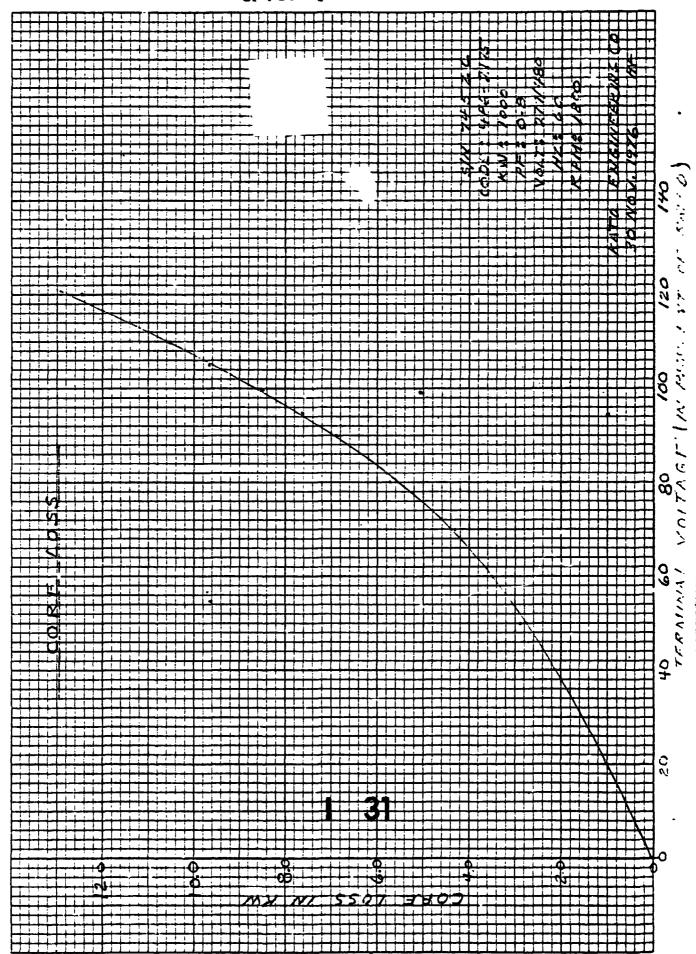
· Total Losses (Watts)

· 100 - 27.03

\$ Eff. = 72.96







				5/4 LCAD	1-1 T-X														,											
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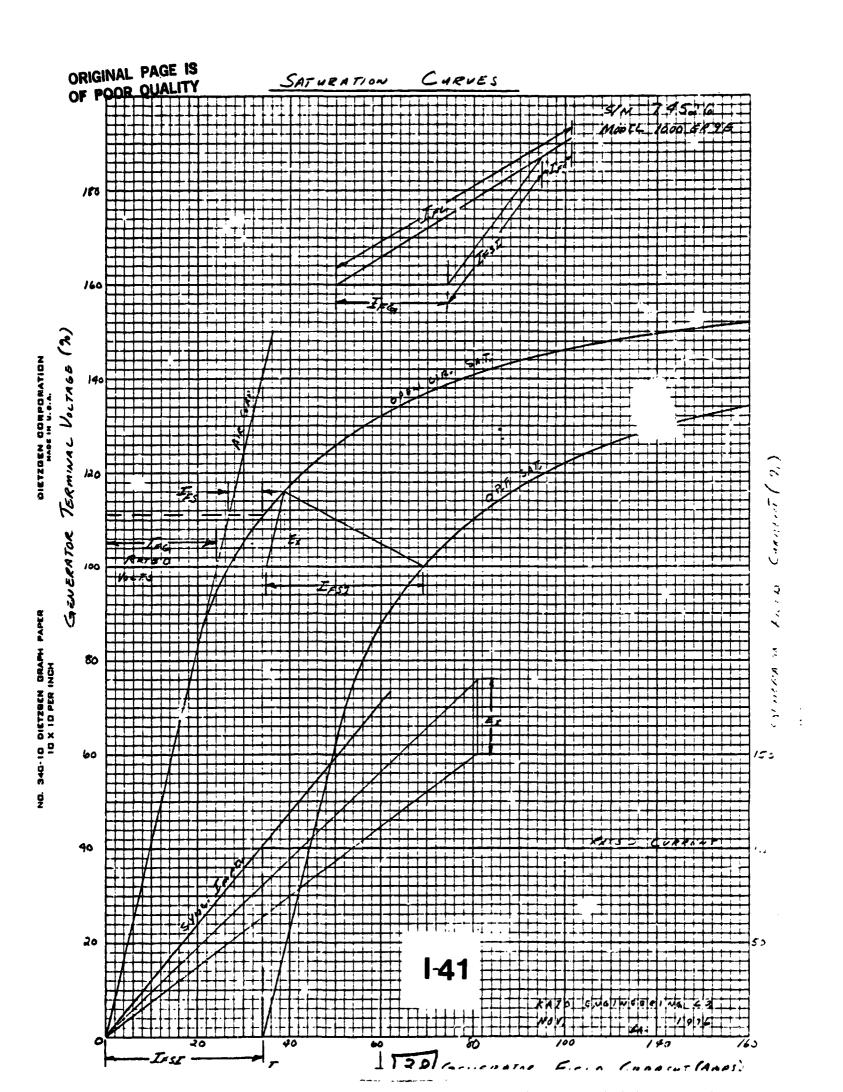
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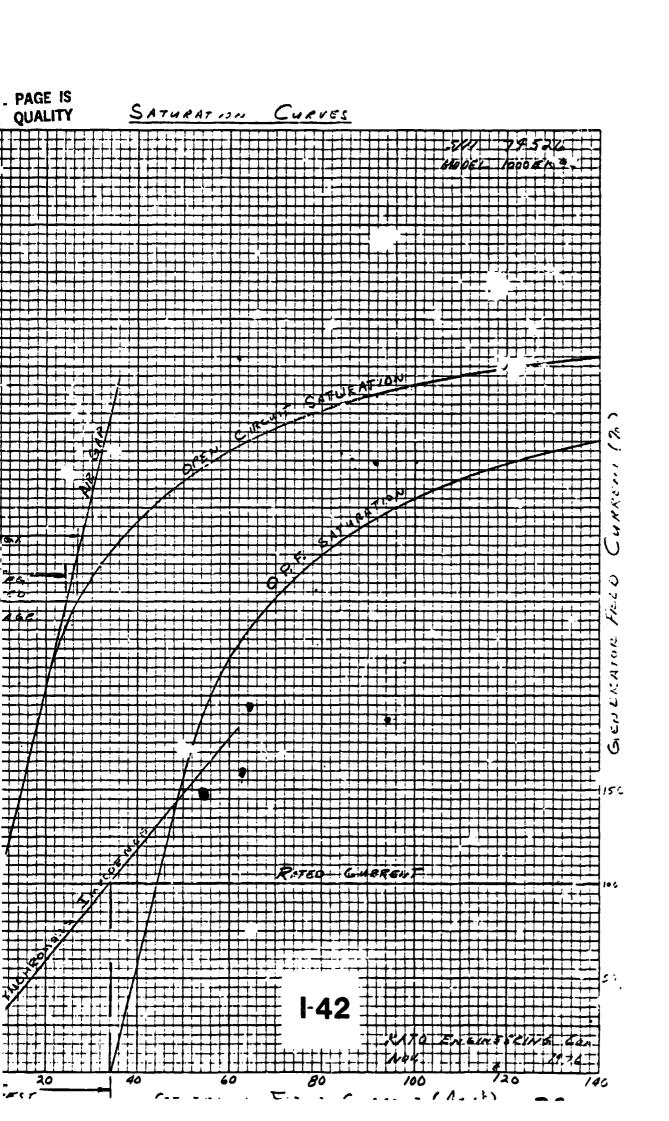
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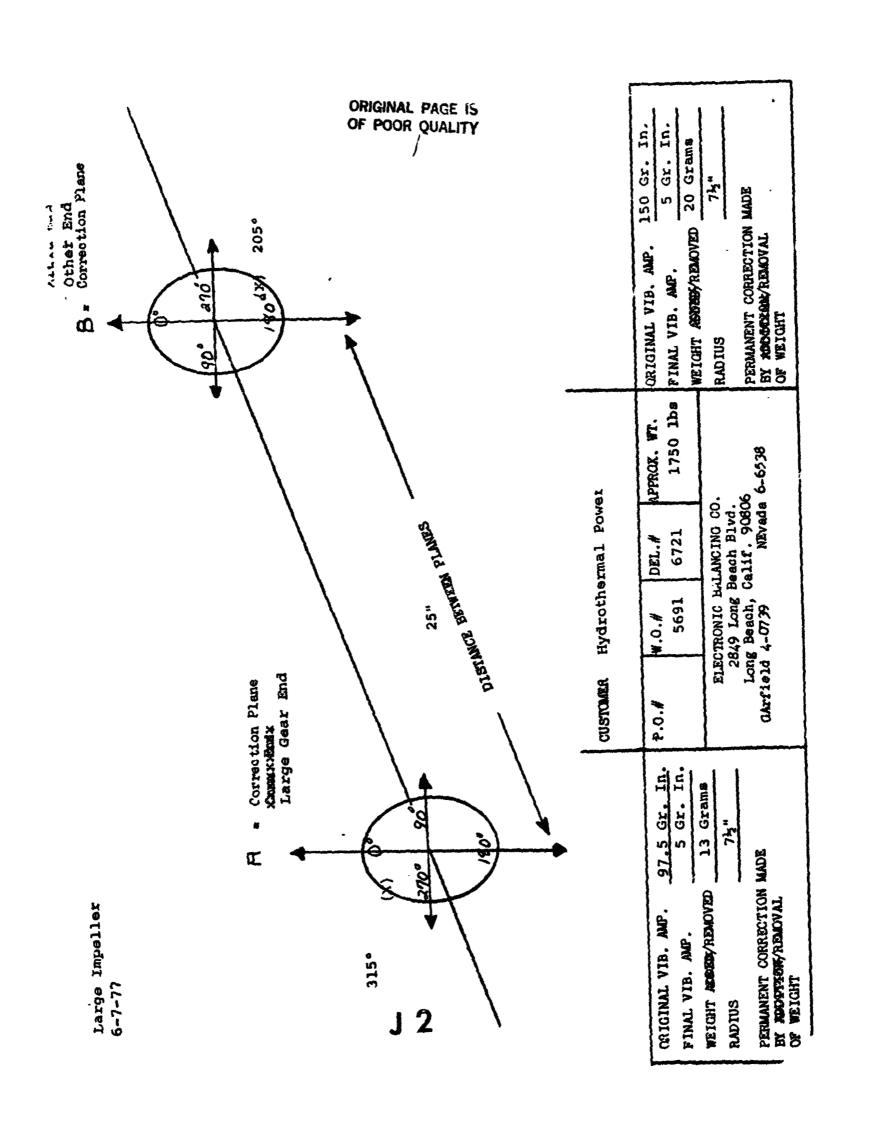
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ACCEPTANCE AND INTERFACE TESTING

A. PURPOSES

- 1. To verify that the HPC Power System 76-1 (a) complies with the contract specifications as embodied in Contract 954404, Exhibit 1, and HPC Drawings B13 and B14, (b) is a complete and functioning subsystem in compliance with HPC Drawing B20, and (c) is ready for delivery to JPL.
- 2. To verify that the interfaces between the HPC Power System 76-1 and the JPL support system are correct and to demonstrate that the Power System and the JPL Control and Instrument Support Van function together as a system.

B. APPROACH

l.		assemble, prepare, and check the Power System in Mission Viejo. The paration should include:
	a.	Preset vibration switches (V_1 , V_2) to NC (normally closed) plus margin at rest. V_1 V_2
	b.	Preset underspeed switch (US) to NO (normally open) at ~ -50 Hz.
	c.	Preset high oil temperature (OHT) switch to NC -150°F.
	đ.	Preset low oil pressure (LOP) switch to NO ≤10-12 psig.
	e.	Preset shaft seal pressure (SSP) switch to NO <125 psig.
	f.	Preset overspeed (OS) switch to NC <2200 RPM = 66 Hz.
	g.	Preset Stop (S) rate for Automatic Stop valve.
	h.	Preset Stop (S) rate for Governor Override.
	i.	Preset Emergency Stop (ES) rate for Automatic Stop valve.
	j.	Preset Emergency Stop (ES) rate for Governor Override.

2. JPL assemble and check the Control and Instrument Support Van equipment and associated cables in Pasadena.

- 3. When both assemblies are ready, transport Van to Mission Viejo. Park along curb toward front of 25721 Obrero and order air compressors for driving Power System. Compressors will arrive in seven days. When they arrive they will park along Obrero toward rear of 25721.
- 4. During wait for compressors, JPL will interface with the Power Systems at the terminal strips TB"EA", TB"EB", and TB"EC" in the junction boxes as shown on HPC Drawing B20. As part of the procedure of interfacing at the terminal strips, each function possible will be checked for end-to-end signal to verify that the JPL and HPC wiring diagrams are correct and correctly executed and that the nomenclature is mutually compatible. Static testing will then be carried out as described under Static Test Procedure, Section C, and the Power System will be checked against Exhibit 1 and HPC Drawings B13 and B14.
- 5. After the compressors arrive, the Dynamic Acceptance and Interface Testing will be performed as described under Dynamic Test Procedures, Sections D and E.
- 6. The Load Bank Interface Testing will not be included in Mission Viejo because of insufficient power. Also science data instrumentation testing for brine parameters, pressure, temperature, and flow rate will be postponed to the field, except that at least two unmounted temperature and pressure measuring devices will be wired and monitored.

ACCEPTANCE AND INTERFACE TESTING (Cont'd.)

C.	STATIC TEST PROCEDURE
1.	Check Batteries
2.	Jumper LOP switch Keep jumpered through step C-22.
3.	Reset Emergency Stop relay to energize the safety shutdown circuit.
4.	Verify that the Exciter switch is in Underspeed Bypass position.
5.	Activate Data Logger and Intercoms log SSP fault
6.	Operate pump #1 to prime lube oil system
7.	Operate pump #2 At 125 psig monitor no fault Pressurize to 150 psig Verify that bearing and winding temperatures, bearing thrust, and throttle position are being logged. See check-list in Appendix.
8.	Momentarily turn (key) Start switch Throttle should open. Observe Log Stop relay should reset
9.	Operate pump #3 to open Automatic Stop valve fully.
10.	Press Stop button at power plant. Observe Throttle ^b and Automatic Stop valve close slowly. Estimate closing time of Automatic Stop valve. Log Throttle ^b position.
11.	Momentarily turn Start switch Throttle ^b should open. Observe Log Stop relay should reset
b -	Throttle response must be verified. It may be necessary to monitor the Governor Override Stop relay isntead.
Date	e: Test Staff:
Note	es:

12.	Press Stop button in V	Estimate closin		
13.	Momentarily turn Start relay should reset.	switch.	Throttle ^b shou	ld open and Stop
14.	Operate pump #3 to ope	en Automatic St	cop valve fully.	
15.	Press Emergency Stop by and Automatic Stop val time of Automatic Stop	lve close rapid	lly.	Estimate closing
16.	Reset Emergency Stop realy reset.	relayC	Observe Throttle ^b Throttle ^b posit	open and Emergency
17.	Press Emergency Stop to and Emergency Stop rel	lay trip	Estima	
18.	Reset Emergency Stop r Stop relay reset.	relay Log	bserve Throttle ^b Throttle ^b position	open and Emergency
19.	Underset or otherwise close and Stop relay to position. Start switch mentarily should reset.	rip. Reset V ₁ . Throt	Log V ₁ fau Log no fau tle ^b should open	lt and Throttle ^D lt Turn and Stop relay
b -	- Throttle response must Governor Override Stop		It may be necess	sary to monitor the
Dat	te: Test	Staff:		
Not	tes:			

20.	Underset or otherwise trip Vibration switch V ₂ Observe Throttle ^b
	close and Stop relay trip Log V ₂ fault and Throttle ^b
	position Reset V ₂ . Log no fault Turn Start
	switch. Observe Throttle ^b open and Stop relay reset.
	Log Throttle ^b position.
21.	Open OHT circuit Observe Throttle ^b close and Stop relay trip Log OHT fault and Throttle ^b position
	Restore OHT circuit Turn Start switch Observe Throttle ^b
	open and Stop relay reset.
22.	Turn Exciter switch to On position to open US bypass. Observe
	Throttle ^b close and Stop relay trip Log US fault and
	Throttle ^b position Turn Exciter switch to US bypass
	Log no fault Turn Start switch Observe Throttleb
	open and Start relay reset. Log Throttle ^b position.
23.	Remove jumper from LOP switchObserve Throttle close and
	Stop relay trip Log LOP fault and Throttle ^b position.
	
24.	Open battery circuit by pressing Emergency Stop buttonLog all
	bearing and winding temperature data Refer to check-list in
	Appendix.
25.	Turn off Data Logger Turn off Intercoms
Ъ-	Throttle response must be verified. It may be necessary to monitor
	the Governor Override Stop instead.
Date	: Test Staff:
Note	25:

ACCEPTANCE AND INTERFACE TESTING (Cont'd.)

D.	DYNAMIC TEST PROCEDURE: MODIFIED START, RUN, STOP
ı ^c .	Deactivate Governor Override relay for Stop circuit Install circuitry with auxiliary switches to permit bypassing the OS switch and place a meter across the OS switch terminals Leave bypass circuit in safety position
2.	Inspect the Power Plant, Van, and Cables for readiness Verify that Main Circuit Breaker is open
3.	Check Batteries.
4.	Reset Emergency Stop relay to energize the safety shutdown circuit.
5.	Verify that Exciter switch is in Underspeed Bypass position.
6.	Verify that Automatic Stop and Manual 8" gate valves are closed.
7.	Turn on compressors (Wear ear protection as necessary.)
8.	Open Manual gate valve fully.
9.	Operate pump #1 to prime lube oil system.
10.	Open shaft guard #1 Manually roll over power train Close guard
c -	This step permits OS switch bypass but retains manual ES shut-down via Governor Override from Power sytem and in Van.
Date	e: Test Staff:
Note	es:

11.	Activate Data Logger and Intercoms Log LOP
	fault and SSP fault
12.	Hold Start switch on. Log SSP fault. Operate pump #2 to provide 150 psig oil. Log no fault. Observe Throttle upen. Log Throttle position. Cycle Exciter switch. Log US fault.
13.	With Start switch still on, operate pump #3 to partly open Automatic Stop valve Rotation should start Watch Tachometer and Brive fluid pressure Watch oil pressure to bearings. Release Start button slightly below LOP setpoint. Deserve Automatic Stop valve close slowly, stopping rotation. Log LOP fault Log engineering data. See check list in Appendix
14.	With Start switch held on, operate pump #3 to partly open Automatic Stop valve Observe rotation Monitor Tachometer and drive fluid pressure. Monitor oil pressure to bearings. Release Start button when oil pressure is above LOP setpoint Observe plant continue to run, throttled by Automatic Stop valve Log no fault
15.	Werify that lube oil reservoir temperature is above 60°F. Otherwise, wait until it is Then continue to open Automatic Stop valve to bring plant to standard operating speed Observe Governor take over Monitor RPM and adjust Governor as necessary. Open Automatic Stop valve slightly more
16.	Partly close Manual gate valve until plant begins to slow Open Automatic Stop valve fully, closing Manual gate valve in alternate increments if necessary to hold plant speed nearly constant
Date	Test Staff:
Note	•

	Transfer speed control to Manual gate valve with Governor adjusted for full Throttle.
17.	Prop Automatic Stop valve about 7/8 open.
18.	With Manual gate valve, adjust speed to standard operating RPM d . Check operation of V_1 two or three times by adjusting sensitivity and adjust for normal plant operation Log V_1 fault and then no fault Observe Automatic Stop valve close against the prop Turn Start switch to reset Stop relay Operate pump #3 to open Automatic Stop valve fully Check operation of V_2 two or three times by adjusting sensitivity and adjust for normal plant operation Log V_2 fault and then no fault
	Observe Automatic Stop valve close against the prop. Turn Start switch to reset Stop relay. Operate pump #3 to open Automatic Stop valve fully.
19.	Bypass OS switch and turn on meter With Manual gate valve and tachometer, check OS trip RPM Note RPM at which trip occurs If t. ɔ does not occur before 11% overspeed, (see Rotor RPM table), set overspeed at 10%, (see table), and adjust OS trip to just open Then reduce RPM gradually to determine RPM at which OS trip closes Verify that OS trip opens on rising RPM Reduce speed to close OS switch and terminate bypass of OS switch During this step, continuously monitor RPM and press Emergency Stop if RPM exceeds 2400 RPM.
d - (or adjust speed to a vibration mode if one appeared during start-up.
Date	: Test Staff:
Note:	s:

Roto	or RPM		
Male		Female	
		Over	speed
		10%	11%
3000	2000	2200	2220
4000	2667	2933	2960
5000	3333	3667	3700
	Male 3000 4000	3000 2000 4000 2667	Male Female Over: 10% 3000 2000 2200 4000 2667 2933

 Date	: Test Staff:
	Adjust frequency to 60 Hz at Power Plant Check remote frequency adjustment capability Check operation of oil cooler fan Direction
25.	Adjust voltage at Power Plant Checkremote voltage adjustment capability
22.	Turn on Exciter. Observe volt meter and frequency meter at Power Plant. Observe same in Van. Log voltage and frequency. Compare.
	Log no fault Turn Start switch to reset Stop relay Operate pump #3 to open Automatic Stop valve fully Remove prop
21.	Open OHT circuit. Log OHT fault. Observe Automatic Stop valve close against the prop. Reconnect OHT circuit.
	(See Rotor RPM table) with Throttle wide open Then reduce speed to standard RPM with Governor and Throttle

Notes:

26.	Check operation of ammeter at Power Plant.
27.	Check Main Circuit Breaker remote trip operation.
28.	Check greaser operation Set pressure at P ₁ + 100 psi
29.	Using Manual gate valve, reduce RPM to monitor US trip speed. Observe Automatic Stop valve close and Plant stop. Log US fault.
30.	Press Emergency Stop button to open battery circuit.
31.	Reactivate Governor Override relay for Stop circuit Remove meter and bypass circuit from Overspeed switch and replace leads on NC terminals
Date	: Test Staff:

Notes:

ACCEPTANCE AND INTERFACE TESTING (Cont'd.)

E.	DYNAMIC TEST PROCEDURE: SEMI-NORMAL START, RUN, STOP
1.	Walk around Plant inspection Verify that Main Circuit Breaker is open
2.	Check battery.
3.	Reset ES relay
4.	Place Exciter switch in US Bypass position Verify that oil cooler fan is in On position
5.	Activate Data Logger and Intercoms Log LOP fault and SSP fault. Log engineering data.
6.	Open Manual gate valve fully.
7.	Operate pump #1 to prime lube oir system.
8.	Operate pump #2 to provide 150 psig oil. LOP fault only.
9.	Hold Start switch on Observe Throttle open
10.	While holding Start switch on, operate pump #3 to open Automatic Stop valve part way. Watch Tachometer and driving pressure. Watch oil pressure to bearings. Release Start switch when pressure exceeds LOP point (~12 psig). Plant will continue to run, throttled by Start/Stop valve.
11.	Verify that lube oil reservoir temperature is above 60°F. Otherwise, wait until it is Then continue. Open Automatic Stop valve to bring Plant to standard operating speed, shifting control to the Governor and Throttle Open Automatic Stop valve fully Monitor RPM and adjust Governor as necessary
Dat	e: Test Staff:
Not	ec.,

12	Turn on Exciter Watch Volumeter and Frequency Meter at Power
	Plant Look for Ammeter response Adjust
	frequencey to 60 Hz with Governor Adjust voltage to 480 V
13.	Check Oil Cooler air flow.
14.	Cycle the Exciter to check the Governor responseMonitor effect on frequency
15.	Operate plant three Lours Log engineering dats Refer to check-list in Appendix. Verify Grease. operation
16.	Press Stop button in van. Observe Automatic Stop valve slowly close and bring Plant to a stop.
17.	Turn off Data Logger Turn off Intercoms
18.	Press ES button to open Battery circuit.
19.	Shut off compressors Bleed off air
20.	Close Manual gate valve
	Test Staff:
Dat	
Not	tes:

APPENDIX
CHECKLIST: ACCEPTANCE AND INTERFACE TESTING GUIDE

ITEM	PRESET	SIGNAL CHECK	STATIC TEST C	DYNAMIC TEST D	DYNAMIC TEST E
v	Bla	В4	C19	D18	
v ₁	Bla	B4	C20	D18	}
v ₂ us	B1b	B4	C4,22	D5,28	
oh:	B1c	B4	C21	D3,28 D21]
LOP	B1d	B4	C2,23	D11,13,	E5,10
1.01	DIG	54	02,23	14	1.5,10
SSP	Ble	B4	C7	D12	E5,8
os	Blf	B4		D19	{
Local S		}	C10		}
Remote S		B4	C12	}	E16
Local Es			C15		!
Remote ES		B4	C17	į	
S rate, valve	Blg	1	C10		
S rate, throttle	Blh	1	C12		
ES rate, valve	Bli	1	C15		1 1
ES rate, throttle	Blj		C17	1	
Governor]		D15	E11,14
Exciter			1	D22	E12
Voltage adjust, local	İ		ĺ	D23	E12
Voltage adjust, remote		B4		D23	
Frequency adjust, local		Į		D24	E12
Frequency adjust, remote		B4	1	D24	1
Ammeter, local				D26] [
Oil Cooler fan		1		D25	E13
Greaser operation			į	D28	E15
Main Breaker trip remot		В4		D27	
Throttle Position		B4	C7	D12	E15
Throttle Bearing 1	ł	B4	C7	D12	E15
" 2	•	B4	C7	D12	E15
Expander Bearing Temp 1		B4	C7	D12	E15

APPENDIX (Cont'd.)

		_			25		
Expander Be	earing To	emp 2		В4	C7	D12	E15
**	**	" 3		В4	C 7	D12	E15
**	**	'' 4		B4	C 7	D12	E15
***	**	'' 5		B4	C7	D12	E15
11	**	**	,	В4	C 7	D12	E15
Alternator	Bearing	Теттр	1	B4	C7	D12	E15
11	**	**	2	В4	C7	D12	E15
11	Winding	**	1	B4	C 7	D12	E15
**	**	**	2	В4	C7	D12	E15
**	**	**	3	В4	C7	D12	E15
**	**	**	4	B4	C 7	D12	E15
**	**	**	5	B4	C 7	D12	E15
**	**	71	6	B4	C7	D12	E15
Intercom				B4	C5	D11	E5
I. remote				B4		D12	E15
KW remote				В4		D12	E15

ACCEPTANCE AND INTERFACL STING (contd)

Not	es:
Dat	e: Test Staff:
7.	Operate pump #1 to prime lube oil system.
	Record cumulative operating time.
6.	Inspect the Power Plant, Van, and Cables for readiness. Verify that Main Circuit Breaker is open Set inhouse breaker off.
5.	Jumper US and OS in Van Log US no fault and OS no fault
4.	Open auxiliary switch in OS switch circuit (near OS switch) Log OS fault
	•
3.	Check for SSP fault, LOP fault, US fault, OS no fault
2.	Activate the data logger and intercoms.
	Place a meter across the OS switch terminals. Leave all three switches in closed (on) position.
	the backup RPM monitor station.)
	jumper requires two switches in series, one at the start station and one at
	output and an auxiliary switch in the OS switch output circuit. The switched
	(This is accomplished by placing a switched jumper across the OS relay
1.	Install circuitry with auxiliary switches to permit bypassing the OS switch.
D.	DYNAMIC TEST PROCEDURE: MODIFIED START, RUN, STOP

Note	s:
Date	: Test Staff:
	plant
	Automatic Stop valve. Log LOP no fault. Observe US fault at
	sure is above LOP setpoint Observe plant continue to run, throttled by
	Monitor oil pressure to bearings Release Start button when oil pres-
10.	Observe rotation Monitor Tachometer and drive fluid pressure.
18.	With Start switch held on, operate pump #3 to partly open Automatic Stop valve.
	fault
	Stop valve start to close slowly. Arrest with Start switch Log LOP
	Release Start button slightly below LOP setpoint. Observe Automatic
	fluid pressure Watch oil pressure to bearings
1/.	valve Rotation should start Watch Tachometer and drive
17.	With Start switch still on, operate pump #3 to partly open Automatic Stop
16.	Hold Start switch on Observe Throttle open.
	Log engineering data See checklist in Appendix.
15.	Check nitrogen pressure Recharge if necessary
14.	Open Manual gate valve about 1/3.
13.	Turn on compressors. (Wear ear protection as necessary.)
12.	Verify that Automatic Stop and Manual 8" gate valves are closed.
11.	Verify that Exciter switch is in Underspeed Bypass position.
10.	Reset Emergency Stop relay to energize the safety shutdown circuit.
9.	Check batteries Close battery switch Log SSP no fault.
	Leave guard open to permit use of surface speed tachometer.
8.	Open shaft guard #1 Manually roll over power train

K16

19.	unt	ify that lube oil reservoir temperature is above 60°F. Otherwise, wait il it is Then continue to open Automatic Stop valve to bring at to standard operating speed according to the following schedule.	
	_	Male rotor 1500 RPM for 10 minutes (1/2 speed). Start time End time	
	ъ.	Transfer control to governor at 1800 RPM.	
	c.	Adjust governor and automatic stop valve alternately to bring speed to 2500 RPM (50 Hz).	
	d.	Excite governor Pring speed to 2750 RPM (55 Hz)	
	e.	Turn on inhouse breaker Check operation of oil fam	
	f.	With governor, slowly bring speed to 3000 RPM (60 Hz) Run 10 minutes under governor control. Start time While running 10 minutes or more at normal speed, perform steps g through k.	
		Adjust voltage at power plant to 480 V Check remote voltage adjustment capability Adjust frequency to 60 Hz at Power Plant panel Check remote frequency adjustment capability	
		Check operation of ammeter at Power Plant.	
		Check greaser operation Set pressure at P ₁ to 100 psi	
	k.	Calibrate tachometer with frequency meter at 60.0 Hz. Tachometer reading. Calculate expected reading for 65.0 Hz and enter in step Calculate expected reading for 66.6 Hz and enter in step 25a.	
Date	:	Test Staff:	

Notes:

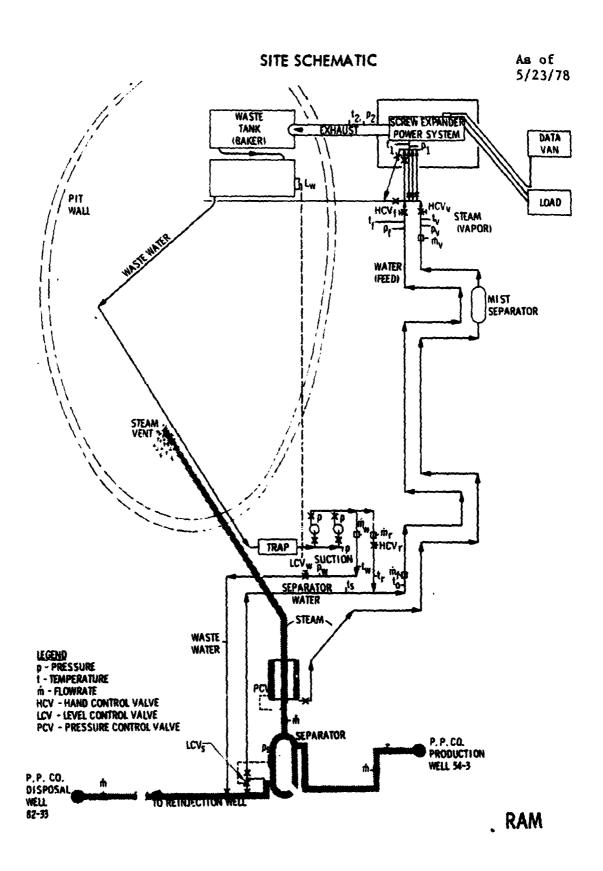
20.	Close Stop metering valve for Automatic Stop valve.
21.	Hold speed to standard operating RPM or adjust speed to a vibration node if one appeared during startup. Check operation of V_1 two or three times by adjusting sensitivity and adjust for normal plant operation Log V_1 fault and then no fault Turn Start switch to reset Stop relay. Check operation of V_2 two or three times by adjusting sensitivity and adjust for normal plant operation Log V_2 fault and then no fault Open Stop metering valve. With speed adjusted to standard (60.0 Hz generator and 3000 RPM male rotor) cycle exciter to monitor speed change Note tachometer speed change.
•	
23.	Turn on voltmeter to monitor OS switch.
24.	Increase speed to 65.0 Hz and check tachometer for correct reading. Theoretical = 3250. Calculated Observed
25.	If observed tachometer reading does not correlate well with the calculated value, step 23, leave exciter on and set OS switch at 65 Hz using frequency meter as speed reference. Adjust OS switch to open at high end of frequency meter Reduce speed with governor and note speed at which OS switch closes Increase speed until OS opens to verify setting Repeat as necessary.
25a.	If observed tachometer reading does correlate well with the calculated value, step 23, turn off exciter and set OS switch using tachometer as speed reference. During this step, continuously monitor RPM and trigger Emergency Stop if RPM exceeds 3450 RPM. Adjust speed to 11% overspeed equal to 3330 RPM male rotor shown on the tachometer as RPM calculated in step 19k.
Date	: Test Staff:
Note	s:

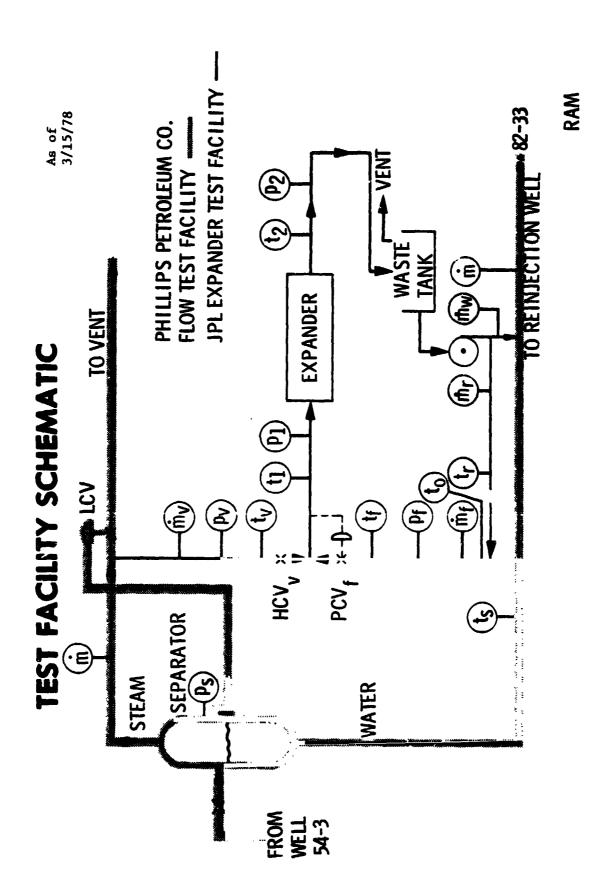
	Set OS switch to just open at this speed Reduce speed with governor
	and note speed at which OS switch closes Increase speed until OS
	opens to verify setting Reduce speed to close switch and
	repeat procedure as necessary.
26.	Reduce speed to normal and excite generator
27.	Terminate bypass of OS switch by first closing bypass switch and then
	opening bypass jumper
28.	Remove US fault signal jumper and OS fault signal jumper in Van.
29.	Using Manual gate valve, reduce RPM to monitor US trip speed.
	Observe Automatic Stop valve start to close Log US fault
	Press ES at RPM = 1500 if possible and monitor Automatic Stop valve.
	Log engineering data at intervals until restart
30.	Open battery circuit
31.	Remove meter from Overspeed signal terminals.
32.	Remove jumper from OS relay output Reconnect lead to OS switch output
	terminal
33.	Close Manual gate valve.
Date	Test Staff:
Note	es:

ACCEPTANCE AND INTERFACE TESTING (Cont'd.)

E.	DYNAMIC TEST PROCEDURE: SEMI-NORMAL START, RUN, STOP
1.	Walk around Plant inspection. Verify that Main Circuit Breaker is open. Place Exciter switch in U.S. bypass position. Set inhouse breaker off.
2.	Manually roll over power train and re-install guard.
3.	Log engineering data.
4.	Operate pump #1 to prime lube oil system.
5.	Close battery switch.
6.	Reset ES relay.
	Open manual gate valve about 1/3 Check nitrogen pressure Recharge if necessary
9.	Hold Start switch on Observe throttle open
10.	While holding Start switch on, operate pump #3 to open Automatic Stop valve part way Watch Tachometer and driving pressure Watch oil pressure to bearings Release Start switch when pressure exceeds LOP point (∿12 psig.) Plant will continue to run, throttled by Start/Stop valve.
11.	Verify that lube oil reservoir temperature is above 60°F. Otherwise, wait until it is Then continue. Open Automatic Stop valve to bring Plant to standard operating speed, shifting control to the Governor and Throttle Open Automatic Stop valve fully Monitor RPM and adjust Governor as necessary
	Date: Test Staff: Notes:

	12.	Turn on ExciterWatch Voltmeter and Frequency Meter at Power
		PlantLook for Ammeter responseAdjust
		frequency to 60 Hz with GovernorAdjust voltage to 480 V
	13.	Check Oil Cooler air flow.
	14.	Cycle the Exciter to check the Governor responseMonitor effect on frequency
	15.	Operate plant three hours. Log engineering data. Refer to check-list in Appendix. Verify Greaser operation.
	16.	Press Stop button in VanObserve Automatic Stop value slowly close and bring Plant to a stop
	17.	Turn off Data LoggerTurn off Intercoms
•	18.	Press ES button to open Battery circuit.
	19.	Shut off compressorsBleed off air
	20.	Close Manual gate valve
	Date	: Test Staff:
	37	
	Note	s:





L2

PROCESS NOMENCLATURE

tr	recycle liquid temperature, of
ts	separator water supply temperature, of
to	combined separator water supply and recycle temperature, of
tf	liquid feed temperature, or
t ₁	expander inlet temperature, of
Q_1	expander inlet quality, %
P1	expander inlet pressure, psia
Pf	liquid feed pressure, psia
T _{sup}	amount of superheat of the steam, OF
$P_{\mathbf{V}}$	steam feed pressure, psia
Ps	separator pressure, psia
Pw	waste liquid pressure to flow control valve
ė _w	waste liquid flowrate, 1000 #/hr
r	recycle liquid flowrate, 1000 #/hr
ms	liquid flowrate from separator, 1000 #/hr (= mf - mr)
mf	liquid flowrate to inlet mixing manifold, #/hr or 1000#/hr
m√	steam flowrate to inlet mixing manifold, #/hr or 1000 #/hr
Ls	liquid level in separator, in.
L _w	liquid level in waste tank, in.
"/h	rate of change of liquid level in waste tanks, in/hr
Trt %	linear throttle position as percent of fully open
kW	electrical output of alternator
freq	frequency of electrical output
eff %	engine efficiency of helical screw expando,, actual shaft power/theoretical shaft power
Brg t	temperature of high speed rotor thrust bearing, of

P2	expander outlet pressure, psia
t ₂	expander outlet temperature, or
Q_2	expander outlet quality (steam fraction), %
t _v	steam feed temperature, OF

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